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A New Look at Dual-Hop Relaying: Performance Limits with Hardware Impairments

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Abstract—Physical transceivers have hardware impairments that create distortions which degrade the performance of communication systems. The vast majority of technical contributions in the area of relaying neglect hardware impairments and, thus, assume ideal hardware. Such approximations make sense in low-rate systems, but can lead to very misleading results when analyzing future high-rate systems. This paper quantifies the impact of hardware impairments on dual-hop relaying, for both amplify-and-forward and decode-and-forward protocols. The outage probability (OP) in these practical scenarios is a function of the effective end-to-end signal-to-noise-and-distortion ratio (SNDR). This paper derives new closed-form expressions for the exact and asymptotic OPs, accounting for hardware impairments at the source, relay, and destination. A similar analysis for the ergodic capacity is also pursued, resulting in new upper bounds. We assume that both hops are subject to independent but non-identically distributed Nakagami- m fading. This paper validates that the performance loss is small at low rates, but otherwise can be very substantial. In particular, it is proved that for high signal-to-noise ratio (SNR), the end-to-end SNDR converges to a deterministic constant, coined the *SNDR ceiling*, which is inversely proportional to the level of impairments. This stands in contrast to the ideal hardware case in which the end-to-end SNDR grows without bound in the high-SNR regime. Finally, we provide fundamental design guidelines for selecting hardware that satisfies the requirements of a practical relaying system.

Index Terms—Amplify-and-forward, decode-and-forward, dual-hop relaying, ergodic capacity, Nakagami- m fading, outage probability, transceiver hardware impairments.

I. INTRODUCTION

THE use of relay nodes for improving coverage, reliability, and quality-of-service in wireless systems has been a hot

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research topic over the past decade, both in academia [2]–[4] and in industry [5], [6]. This is due to the fact that, unlike macro base stations, relays are low-cost nodes that can be easily deployed and, hence, enhance the network agility. The vast majority of works in the context of relaying systems make the standard assumption of ideal transceiver hardware.

However, in practice, hardware suffers from several types of impairments; for example, phase noise, I/Q imbalance, and high power amplifier (HPA) nonlinearities among others [7]–[9]. The impact of hardware impairments on various types of single-hop systems was analyzed in [7]–[19]. For instance, I/Q imbalance was considered in [12] and it was shown to attenuate the amplitude and rotate the phase of the desired constellation. Moreover, it creates an additional image-signal from the mirror subcarrier, which leads to a symbol error rate floor. In addition, [13] characterized the effect of non-linear HPAs as a distortion of the constellation position plus an additive Gaussian noise. The authors therein showed that, in the presence of HPA non-linearities, the bit-error-rate increases compared to linear HPAs; for severe non-linearities, an irreducible error floor emerges. Hardware impairments are typically mitigated by compensation algorithms, but there are always residual impairments [8]–[10]. As a general conclusion, hardware impairments have a deleterious impact on the achievable performance [10]–[19]. This effect is more pronounced in high-rate systems, especially those employing inexpensive hardware [8]. Recent works in information theory have demonstrated that non-ideal hardware severely affects multi-antenna systems; more specifically, [18] proved that there is a finite capacity limit at high signal-to-noise ratio (SNR), while [19] provided a general resource allocation framework where existing signal processing algorithms are redesigned to account for impairments.

Despite the importance of transceiver hardware impairments, their impact on one-way relaying¹ has only been partially investigated; bit error rate simulations were conducted in [15] for amplify-and-forward (AF) relaying, while [16], [17] derived expressions for the bit/symbol error rates considering only non-linearities or I/Q imbalance, respectively. Most recently, [21], [22] elaborated on the impact of I/Q imbalance on AF relaying and suggested novel digital base-band compensation algorithms. In this paper, we follow a different line of reasoning by providing a detailed performance analysis of dual-hop relaying systems in the presence of *aggregate transceiver impairments*, both for AF and decode-

¹Analysis of two-way AF relaying was conducted in our recent paper [20].

and-forward (DF) protocols. To the best of our knowledge, this is the first paper presenting an analytical study of relaying with transceiver impairments under the generalized system model of [8]–[11]. The paper makes the following specific contributions:

- We introduce a general model to account for transceiver hardware impairments in relaying. Unlike the works of [16], [17], [21], [22], which examined the impact of a single type of impairments, we herein take a macroscopic look and investigate the aggregate impact of hardware impairments.
- After obtaining the instantaneous end-to-end signal-to-noise-plus-distortion ratios (SNDRs) for both AF and DF relaying, we derive new closed-form expressions for the exact outage probability (OP) of the system. This enables us to characterize the impact of impairments for any arbitrary SNR value. New upper bounds on the ergodic capacity are also provided. Note that our analysis considers Nakagami- m fading, which has been extensively used in the performance analysis of communication systems.
- In order to obtain more engineering insights, we elaborate on the high-SNR regime and demonstrate the presence of a so-called SNDR ceiling. This fundamental ceiling is explicitly quantified and its value is shown to be inversely proportional to the level of impairments. This observation manifests that both AF and DF relaying systems are intimately limited by hardware impairments—especially at high SNRs and when high rates are desirable. On a similar note, the ergodic capacity exhibits a so-called capacity ceiling.
- In the last part of the paper, we provide some design guidelines for optimizing the performance of hardware-constrained relaying systems. These results are of particular importance when it comes down to finding the *lowest* hardware quality (i.e., *highest* level of impairments) that can theoretically meet stipulated requirements.

The remainder of the paper is organized as follows: In Section II, the signal and system models, for both ideal and impaired hardware, are outlined. For the sake of generality, we consider both dual-hop AF and DF relaying and assume that both hops are subject to independent and non-identically distributed fading. In Section III, an OP analysis is pursued that can be applied for any type of fading and is specialized to the cases of Nakagami- m and Rayleigh fading. A similar analysis for the ergodic capacity is performed in Section IV, which results in new upper bounds. The performance limits of hardware-constrained relaying systems in the high-SNR regime are examined in Section V and some fundamental design guidelines are also obtained. Our numerical results are provided in Section VI, while Section VII concludes the paper.

A. Notation

Circularly-symmetric complex Gaussian distributed variables are denoted as $x \sim \mathcal{CN}(a, b)$ where a is the mean value and $b > 0$ is the variance. Gamma distributed variables are denoted as $\rho \sim \text{Gamma}(\alpha, \beta)$, where $\alpha \geq 0$ is the shape parameter and $\beta > 0$ is the scale parameter. The expectation operator is denoted $\mathbb{E}\{\cdot\}$ and $\Pr\{\mathcal{A}\}$ is the probability of an

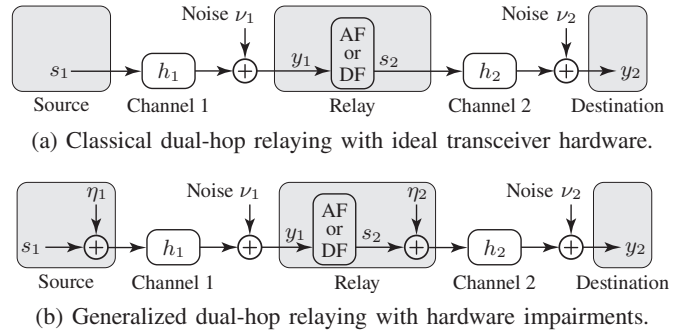


Fig. 1: Block diagram of AF/DF relaying with (a) ideal hardware or (b) non-ideal hardware with transceiver impairments modeled by the aggregate distortion noises η_1, η_2 .

event \mathcal{A} . The operator \triangleq denotes a definition. The gamma function $\Gamma(n)$ of an integer n satisfies $\Gamma(n) = (n - 1)!$.

II. SIGNAL AND SYSTEM MODEL

This paper revisits classical dual-hop relaying where a source communicates with a destination through a relay; see Fig. 1(a). There is no direct link between the source and the destination (e.g., due to heavy shadowing), but the results herein can be extended to that scenario as well. Contrary to most prior works, we consider a generalized system model that accounts for transceiver hardware impairments. This model is described in the following subsections and the block model is shown in Fig. 1(b).

A. Preliminaries on Distortion Noise from Impairments

We first describe a generalized system model for single-hop transmission that originates from [8]–[11]. Suppose an information signal $s \in \mathbb{C}$ is conveyed over a flat-fading wireless channel $h \in \mathbb{C}$ with additive noise $\nu \in \mathbb{C}$. This channel can, for example, be one of the subcarriers in a multi-carrier system based on orthogonal frequency-division multiplexing (OFDM) [23]. The received signal is conventionally modeled as

$$y = hs + \nu \quad (1)$$

where h , s , and ν are statistically independent. However, physical radio-frequency (RF) transceivers suffer from impairments that are not accurately captured in this way. Informally speaking, such impairments 1) create a mismatch between the intended signal s and what is actually generated and emitted; and 2) distort the received signal during the reception processing. This calls for the inclusion of additional distortion noise sources that are statistically dependent on the signal power and channel gain.

Detailed distortion models are available for different sources of impairments (e.g., I/Q imbalance, HPA non-linearities, and phase-noise); see [8] for a detailed description of hardware impairments in OFDM systems and related compensation algorithms. However, the combined influence at a given flat-fading subcarrier is often well-modeled by a generalized channel model [8], where the received signal becomes

$$y = h(s + \eta_t) + \eta_r + \nu \quad (2)$$

while η_t, η_r are *distortion noises* from impairments in the transmitter and receiver, respectively [8]. The distortion noises are defined as

$$\eta_t \sim \mathcal{CN}(0, \kappa_t^2 P), \quad \eta_r \sim \mathcal{CN}(0, \kappa_r^2 P |h|^2) \quad (3)$$

which is a model that has been supported and validated by many theoretical investigations and measurements (see e.g., [9]–[11], [13], [24] and references therein). The design parameters $\kappa_t, \kappa_r \geq 0$ are described below. The joint Gaussianity in (3) is explained by the aggregate effect of many impairments.² For a given channel realization h , the aggregate distortion seen at the receiver has power

$$\mathbb{E}_{\eta_t, \eta_r} \{|h\eta_t + \eta_r|^2\} = P|h|^2(\kappa_t^2 + \kappa_r^2). \quad (4)$$

Thus, it depends on the average signal power $P = \mathbb{E}_s\{|s|^2\}$ and the instantaneous channel gain $|h|^2$. Note that this dependence is not supported by the classical channel model in (1), because the effective distortion noise is correlated with the channel and is not Gaussian distributed.³

The design parameters $\kappa_t, \kappa_r \geq 0$ characterize the *level of impairments* in the transmitter and receiver hardware, respectively. These parameters are interpreted as the error vector magnitudes (EVMs). EVM is a common quality measure of RF transceivers and is the ratio of the average distortion magnitude to the average signal magnitude.⁴ Since the EVM measures the joint impact of different hardware impairments and compensation algorithms, it can be measured directly in practice (see e.g., [26]). As seen from (4) it is sufficient to characterize the *aggregate level of impairments* $\kappa = \sqrt{\kappa_t^2 + \kappa_r^2}$ of the channel, without specifying the exact contribution from the transmitter hardware (κ_t) and the receiver hardware (κ_r). This observation is now formalized.

Lemma 1: The generalized channel in (2) is equivalent to

$$y = h(s + \eta) + \nu \quad (5)$$

where the independent distortion noise $\eta \sim \mathcal{CN}(0, \kappa^2 P)$ describes contributions from hardware impairments at both the transmitter and the receiver, such that $\kappa \triangleq \sqrt{\kappa_t^2 + \kappa_r^2}$.

The single-parameter characterization in Lemma 1 is used henceforth for the sake of brevity and without loss of generality. Note that (5) reduces to the classical model in (1) when $\kappa = 0$, which represents ideal transmitter and receiver hardware since it implies that $\kappa_t = \kappa_r = 0$.

²Note that the Gaussian assumption holds particularly well for the residual distortion when compensation algorithms are applied to mitigate hardware impairments [9].

³The effective distortion noise can be seen as two independent jointly Gaussian variables η_t and η_r/h that are multiplied with the fading channel h . The effective distortion noise is thus only complex Gaussian distributed when conditioning on a channel realization, while the true distribution is the product of the complex Gaussian distribution of the distortion noise and the channel fading distribution. This becomes a *complex double Gaussian* distribution under Rayleigh fading [25], while the distribution under Nakagami- m fading does not admit any known statistical characterization.

⁴The EVM at the transmitter is defined as $\sqrt{\mathbb{E}_{\eta_t}\{|\eta_t|^2\}/\mathbb{E}_s\{|s|^2\}}$ [26]. 3GPP LTE has EVM requirements in the range $\kappa_t \in [0.08, 0.175]$, where smaller values are needed to support the highest spectral efficiencies [27, Sec. 14.3.4].

B. System Model: Relaying with Non-Ideal Hardware

Consider the dual-hop relaying scenario in Fig. 1. Let the transmission parameters between the source and the relay have subscript 1 and between relay and destination have subscript 2. Using the generalized system model in Lemma 1, the received signals at the relay and destination are

$$y_i = h_i(s_i + \eta_i) + \nu_i, \quad i = 1, 2 \quad (6)$$

where $s_1, s_2 \in \mathbb{C}$ are the transmitted signals from the source and relay, respectively, with average signal power $P_i = \mathbb{E}_{s_i}\{|s_i|^2\}$. In addition, $\nu_i \sim \mathcal{CN}(0, N_i)$ represents the complex Gaussian receiver noise and $\eta_i \sim \mathcal{CN}(0, \kappa_i^2 P_i)$ is the distortion noise (introduced in Section II-A), for $i = 1, 2$. The distortion noise from hardware impairments (after conventional compensation algorithms have been applied) acts as an unknown noise-like interfering signal η_i that goes through the same channel h_i as the intended signal, thus making (6) fundamentally different from a conventional multiple-access channel, where each user signal experiences independent channel fading.

The channel magnitudes $|h_i|$ are modeled as independent but non-identically distributed Nakagami- m variates, such that the channel gains $\rho_i \triangleq |h_i|^2 \sim \text{Gamma}(\alpha_i, \beta_i)$. These are Gamma distributed with integer⁵ shape parameters $\alpha_i \geq 1$ and arbitrary scale parameters $\beta_i > 0$.⁶ In this case, the cumulative distribution functions (cdfs) and probability distribution functions (pdfs) of the channel gains, ρ_i , are

$$F_{\rho_i}(x) = 1 - \sum_{j=0}^{\alpha_i-1} \frac{e^{-\frac{x}{\beta_i}}}{j!} \left(\frac{x}{\beta_i}\right)^j, \quad x \geq 0 \quad (7)$$

$$f_{\rho_i}(x) = \frac{x^{\alpha_i-1} e^{-\frac{x}{\beta_i}}}{\Gamma(\alpha_i) \beta_i^{\alpha_i}}, \quad x \geq 0 \quad (8)$$

for $i = 1, 2$. Note that most of the analysis in this paper is generic and applies for any fading distribution. The choice of Nakagami- m fading is only exploited for deriving closed-form expressions for quantities such as the OP and ergodic capacity. For any fading distribution, the quantity

$$\text{SNR}_i = \frac{P_i \mathbb{E}_{\rho_i}\{\rho_i\}}{N_i} \quad (9)$$

is referred to as the *average SNR*, for $i = 1, 2$. The average fading power is $\mathbb{E}_{\rho_i}\{\rho_i\} = \alpha_i \beta_i$ under Nakagami- m fading.

Remark 1 (High SNR): The level of impairment κ_i depends on the SNR [11], [19], [29]. In most of our analysis, we consider an arbitrary fixed SNR_i and thus κ_i can be taken as a constant. However, some remarks are in order for our high-SNR analysis in Section V. As seen from (9), a high SNR can be achieved by having high signal power P_i and/or high fading power $\mathbb{E}_{\rho_i}\{\rho_i\}$. If we increase the signal power to operate outside the dynamic range of the power amplifier, then the level of impairments κ_i increases as well due to the HPA

⁵The assumption of integer shape parameters is made to facilitate the, otherwise tedious, algebraic manipulations for the Nakagami- m fading case.

⁶We recall that Nakagami- m fading reduces to the classical Rayleigh fading with variance Ω_i when $\alpha_i = 1$ and $\beta_i = \Omega_i$; thus, Nakagami- m fading brings more degrees-of-freedom for describing practical propagation environments and has been shown to provide better fit with real measurement results in various multipath channels [28].

nonlinearities [29]. Advanced dynamic power adaptation is then required to maximize the performance [14]. If we, on the other hand, increase the fading power (e.g., by decreasing the propagation loss) then it has no impact on κ_i . For brevity, we keep the analysis clean by assuming that any change in SNR is achieved by a change in the average fading power, while the signal power is fixed. We stress that the upper bounds and necessary conditions derived in Section V are also valid when the signal power is increased, but then they will be optimistic and no longer tight in the high-SNR regime.

In the next subsections, we derive the end-to-end SNDRs for AF and DF relaying, respectively.

C. End-to-End SNDR: Amplify-and-Forward Relaying

The information signal s_1 should be acquired at the destination. In the AF relaying protocol, the transmitted signal s_2 at the relay is simply an amplified version of the signal y_1 received at the relay: $s_2 = G y_1$ for some amplification factor $G > 0$. With non-ideal (ni) hardware, as described by (6), the received signal at the destination is now obtained as

$$y_2 = h_2 G_{\text{ni}} \left(h_1 (s_1 + \eta_1) + \nu_1 \right) + h_2 \eta_2 + \nu_2 \quad (10)$$

$$= G_{\text{ni}} h_1 h_2 s_1 + G_{\text{ni}} h_1 h_2 \eta_1 + G_{\text{ni}} h_2 \nu_1 + h_2 \eta_2 + \nu_2$$

where the amplification factor G_{ni} is selected at the relay to satisfy its power constraint. The source needs no channel knowledge. If the relay has instantaneous knowledge of the fading channel, h_1 , it can apply variable gain relaying with $G^v \triangleq \sqrt{P_2 / \mathbb{E}_{s_1, \nu_1, \eta_1} \{|y_1|^2\}}$ [30]. Otherwise, fixed gain relaying with $G^f \triangleq \sqrt{P_2 / \mathbb{E}_{s_1, \nu_1, \eta_1, h_1} \{|y_1|^2\}}$ can be applied using only statistical channel information [3].⁷ For fixed and variable gain relaying, G_{ni} reads respectively as

$$G_{\text{ni}}^f \triangleq \sqrt{\frac{P_2}{P_1 \mathbb{E}_{\rho_1} \{\rho_1\} (1 + \kappa_1^2) + N_1}} \quad (11)$$

$$G_{\text{ni}}^v \triangleq \sqrt{\frac{P_2}{P_1 \rho_1 (1 + \kappa_1^2) + N_1}} \quad (12)$$

where $\mathbb{E}_{\rho_1} \{\rho_1\} = \alpha_1 \beta_1$ for Nakagami- m fading.

Note that variable gain relaying has always an output power of P_2 at the relay, whilst for fixed gain relaying this varies with the channel gain of the first hop. This, in turn, affects the variance of the distortion noise η_2 for the second hop, which by definition is $\mathbb{E}\{|\eta_2|^2\} = \kappa_2^2 G_{\text{ni}}^2 \mathbb{E}_{s_1, \nu_1} \{|y_1|^2\}$ for AF relaying. This reduces to the simple expression $\kappa_2^2 P_2$ for variable gain relaying, while it becomes $(G_{\text{ni}}^f)^2 \kappa_2^2 (P_1 \rho_1 (1 + \kappa_1^2) + N_1)$ for fixed gain relaying.

After some algebraic manipulations (e.g., using the expressions for G_{ni}^v), the end-to-end SNDRs for fixed and variable gain relaying are obtained as

$$\gamma_{\text{ni}}^{\text{AF-f}} = \frac{\rho_1 \rho_2}{\rho_1 \rho_2 d + \rho_2 (1 + \kappa_2^2) \frac{N_1}{P_1} + \frac{N_2}{P_1 (G_{\text{ni}}^f)^2}} \quad (13)$$

$$\gamma_{\text{ni}}^{\text{AF-v}} = \frac{\rho_1 \rho_2}{\rho_1 \rho_2 d + \rho_1 (1 + \kappa_1^2) \frac{N_2}{P_2} + \rho_2 (1 + \kappa_2^2) \frac{N_1}{P_1} + \frac{N_1 N_2}{P_1 P_2}} \quad (14)$$

⁷The relay then has a long-term power constraint $P_2 = \mathbb{E}\{|G^f y_1|^2\}$ where expectation is taken over signal, noise, and channel fading realizations.

respectively, assuming that the destination knows the two channels and the statistics of the receiver and distortion noises. Note that the parameter $d \triangleq \kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2$ that appears in (13)–(14) plays a key role in this paper.

Remark 2 (Ideal Hardware): The end-to-end SNRs for AF relaying with ideal (id) hardware were derived in [3], [30]. The results of this section reduce to that special case when setting $\kappa_1 = \kappa_2 = 0$. The amplification factors then become

$$G_{\text{id}}^f = \sqrt{\frac{P_2}{P_1 \mathbb{E}_{\rho_1} \{\rho_1\} + N_1}}, \quad G_{\text{id}}^v = \sqrt{\frac{P_2}{P_1 \rho_1 + N_1}} \quad (15)$$

and the end-to-end SNRs become

$$\gamma_{\text{id}}^{\text{AF-f}} = \frac{\rho_1 \rho_2}{\rho_2 \frac{N_1}{P_1} + \frac{N_2}{P_1 (G_{\text{id}}^f)^2}}, \quad \gamma_{\text{id}}^{\text{AF-v}} = \frac{\rho_1 \rho_2}{\rho_1 \frac{N_2}{P_2} + \rho_2 \frac{N_1}{P_1} + \frac{N_1 N_2}{P_1 P_2}} \quad (16)$$

for fixed and variable gain relaying, respectively. Comparing the SNDRs in (13)–(14) with the ideal hardware case in (16), the mathematical form of the former is more complicated, since the product $\rho_1 \rho_2$ appears in the denominator. It is, therefore, non-trivial to generalize prior works on AF relaying with Nakagami- m fading (e.g., [4], [31], [32]) to the general case of non-ideal hardware. This generalization is done in Section III and is a main contribution of this paper.

D. End-to-End SNDR: Decode-and-Forward Relaying

In the DF relaying protocol, the transmitted signal s_2 at the relay should equal the original intended signal s_1 . This is only possible if the relay is able to decode the signal (otherwise the relayed signal is useless); thus, the effective SNDR is the minimum of the SNDRs between 1) the source and relay; and 2) the relay and destination. We assume that the relay knows h_1 and the destination knows h_2 , along with the statistics of the receiver and distortion noises.

With non-ideal hardware as described by (6), the effective end-to-end SNDR becomes

$$\gamma_{\text{ni}}^{\text{DF}} = \min \left(\frac{P_1 \rho_1}{P_1 \rho_1 \kappa_1^2 + N_1}, \frac{P_2 \rho_2}{P_2 \rho_2 \kappa_2^2 + N_2} \right) \quad (17)$$

and does not require any channel knowledge at the source. In the special case of ideal hardware (i.e., $\kappa_1 = \kappa_2 = 0$), (17) reduces to the classical result from [2]; that is

$$\gamma_{\text{id}}^{\text{DF}} = \min \left(\frac{P_1 \rho_1}{N_1}, \frac{P_2 \rho_2}{N_2} \right). \quad (18)$$

Just as for AF relaying, the SNDR expression with DF relaying is more complicated in the general case with hardware impairments. This is manifested in (17) by the statistical dependence between numerators and denominators, which is different from the ideal case in (18).

III. OUTAGE PROBABILITY ANALYSIS

This section derives new closed-form expressions for the exact OPs under the presence of transceiver impairments. These results generalize the well known results in the literature, such as [2]–[4], [31], [32], which rely on the assumption of ideal hardware. The OP is denoted by $P_{\text{out}}(x)$ and is the probability that the channel fading makes the effective end-to-end SNDR

fall below a certain threshold, x , of acceptable communication quality. Mathematically speaking, this means that

$$P_{\text{out}}(x) \triangleq \Pr\{\gamma \leq x\} \quad (19)$$

where γ is the effective end-to-end SNDR.

A. Arbitrary Channel Fading Distributions

This subsection derives general expressions for the OP that hold true for any distributions of the channel gains ρ_1, ρ_2 . These offer useful tools, which later will allow us to derive closed-form expressions for the cases of Nakagami- m and Rayleigh fading. Note that ρ_1, ρ_2 appear in both numerators and denominators of the SNDRs in (13)–(14) and (17). The following lemma enable us to characterize this structure.

Lemma 2: Let c_1, c_2, c_3 be strictly positive constants and let ρ be a non-negative random variable with cdf $F_\rho(\cdot)$. Then,

$$\Pr\left\{\frac{c_1\rho}{c_2\rho + c_3} \leq x\right\} = \begin{cases} F_\rho\left(\frac{c_3x}{c_1 - c_2x}\right), & 0 \leq x < \frac{c_1}{c_2}, \\ 1, & x \geq \frac{c_1}{c_2}. \end{cases} \quad (20)$$

Suppose $c_2 = 0$ instead, then (20) simplifies to

$$\Pr\left\{\frac{c_1\rho}{c_3} \leq x\right\} = F_\rho\left(\frac{c_3x}{c_1}\right). \quad (21)$$

Proof: The left-hand side of (20) is equal to

$$\Pr\left\{c_1\rho \leq (c_2\rho + c_3)x\right\} = \Pr\left\{\rho \leq \frac{c_3x}{(c_1 - c_2x)}\right\} \quad (22)$$

after some basic algebra. The last expression is exactly $F_\rho\left(\frac{c_3x}{c_1 - c_2x}\right)$. If $(c_1 - c_2x) \leq 0$, then the inequality is satisfied for any realization of the non-negative variable ρ . ■

Based on Lemma 2, we can derive integral expressions for the OPs with AF relaying.

Proposition 1: Suppose ρ_i is an independent non-negative random variable with cdf $F_{\rho_i}(\cdot)$ and pdf $f_{\rho_i}(\cdot)$ for $i = 1, 2$. The OP with AF relaying and non-ideal hardware is

$$P_{\text{out}}^{\text{AF,ni}}(x) = 1 - \int_0^\infty \left(1 - F_{\rho_1}\left(\frac{b_2x}{(1-dx)} + \frac{b_1b_2x^2 + cx}{z(1-dx)}\right)\right) f_{\rho_2}\left(z + \frac{b_1x}{1-dx}\right) dz \quad (23)$$

for $x < \frac{1}{d}$ and $P_{\text{out}}^{\text{AF,ni}}(x) = 1$ for $x \geq \frac{1}{d}$. Recall that $d \triangleq \kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2$. The choice of AF protocol determines b_1, b_2, c :

$$\begin{cases} b_1 = 0, b_2 = \frac{N_1(1+\kappa_2^2)}{P_1}, c = \frac{N_2}{P_1(G_{\text{ni}}^2)^2} & \text{if fixed gain,} \\ b_1 = \frac{N_2(1+\kappa_1^2)}{P_2}, b_2 = \frac{N_1(1+\kappa_2^2)}{P_1}, c = \frac{N_1N_2}{P_1P_2} & \text{if variable gain.} \end{cases}$$

In the special case of ideal hardware, (23) reduces to

$$P_{\text{out}}^{\text{AF,id}}(x) = 1 - \int_0^\infty \left(1 - F_{\rho_1}\left(b_2x + \frac{b_1b_2x^2 + cx}{z}\right)\right) f_{\rho_2}(z + b_1x) dz \quad (24)$$

where the parameters b_1, b_2, c, d depend on the AF protocol:

$$\begin{cases} b_1 = 0, b_2 = \frac{N_1}{P_1}, c = \frac{N_2}{P_1(G_{\text{id}}^2)^2}, d = 0 & \text{if fixed gain,} \\ b_1 = \frac{N_2}{P_2}, b_2 = \frac{N_1}{P_1}, c = \frac{N_1N_2}{P_1P_2}, d = 0 & \text{if variable gain.} \end{cases}$$

Proof: The proof follows from Lemma 2 and Lemma 3 in Appendix A, by noting that the end-to-end SNDRs for non-ideal hardware in (13)–(14) and ideal hardware in (16), are of the form in (46) for different values of a, b_1, b_2, c, d . ■

The result in Lemma 2 also allows explicit expressions for the OPs with DF relaying.

Proposition 2: Suppose ρ_i is an independent non-negative random variable with cdf $F_{\rho_i}(\cdot)$ for $i = 1, 2$. The OP with DF relaying and non-ideal hardware is

$$P_{\text{out}}^{\text{DF,ni}}(x) = \begin{cases} 1 - \prod_{i=1}^2 \left(1 - F_{\rho_i}\left(\frac{N_i x}{P_i(1-\kappa_i^2 x)}\right)\right), & x < \frac{1}{\delta}, \\ 1, & x \geq \frac{1}{\delta}, \end{cases} \quad (25)$$

with $\delta \triangleq \max(\kappa_1^2, \kappa_2^2)$. In the special case of ideal hardware, (25) reduces to

$$P_{\text{out}}^{\text{DF,id}}(x) = 1 - \prod_{i=1}^2 \left(1 - F_{\rho_i}\left(\frac{N_i x}{P_i}\right)\right). \quad (26)$$

Proof: For a set of independent random variables ξ_i with marginal cdfs $F_{\xi_i}(x)$, the random variable $\min_i(\xi_i)$ has cdf $1 - \prod_i(1 - F_{\xi_i}(x))$. The proof follows by combining this standard property with Lemma 2 and (17)–(18). ■

Note that the OP expressions in Propositions 1 and 2 allow the straightforward computation of the OP for any channel fading distribution, either directly (for DF) or by a simple numerical integration (for AF). In Section III-B, we particularize these expressions to the cases of Nakagami- m and Rayleigh fading to obtain closed-form results.

Interestingly, Propositions 1 and 2 show that the OP, $P_{\text{out}}(x)$, is always 1 for $x \geq \frac{1}{d}$ when using AF and 1 for $x \geq \frac{1}{\delta}$ when using DF. Note that these results hold for any channel fading distribution and SNR; hence, there are certain SNDR thresholds that can never be crossed. This has an intuitive explanation since the SNDRs derived in Section II are upper bounded as $\gamma_{\text{ni}}^{\text{AF}} \leq \frac{1}{d}$ and $\gamma_{\text{ni}}^{\text{DF}} \leq \frac{1}{\delta}$. We elaborate further on this fundamental property in Section V.

B. Nakagami- m and Rayleigh Fading Channels

Under ideal hardware, the OPs with fixed and variable gain AF relaying were obtained in [3, Eq. (9)] and [30, Eq. (14)], respectively. These prior works considered Rayleigh fading, while closed-form expression for the case of Nakagami- m fading were obtained in [4], [31], [32] under ideal hardware. Unfortunately, the OP in the general AF relaying case with non-ideal hardware cannot be deduced from these prior results; for example, the general analysis in [32] does not handle cases when $\rho_1\rho_2$ appears in the denominator of the SNDR expression, which is the case in (13)–(14).

The following key theorem provides new and tractable closed-form OP expressions in the presence of transceiver hardware impairments.

Theorem 1: Suppose ρ_1, ρ_2 are independent and $\rho_i \sim \text{Gamma}(\alpha_i, \beta_i)$ where $\alpha_i \geq 1$ is an integer and $\beta_i > 0$ for

$i = 1, 2$. The OP with AF relaying and non-ideal hardware is

$$P_{\text{out}}^{\text{AF,ni}}(x) = 1 - 2e^{-\frac{x}{1-dx}} \left(\frac{b_1}{\beta_2} + \frac{b_2}{\beta_1}\right) \sum_{j=0}^{\alpha_1-1} \sum_{n=0}^{\alpha_2-1} \sum_{k=0}^j C(j, n, k) \times \left(\frac{x}{1-dx}\right)^{\alpha_2+j} \left(b_1 b_2 + \frac{c(1-dx)}{x}\right)^{\frac{n+k+1}{2}} \times K_{n-k+1} \left(2\sqrt{\frac{b_1 b_2 x^2}{\beta_1 \beta_2 (1-dx)^2} + \frac{cx}{\beta_1 \beta_2 (1-dx)}}\right) \quad (27)$$

for $x < \frac{1}{d}$ and $P_{\text{out}}^{\text{AF,ni}}(x) = 1$ for $x \geq \frac{1}{d}$. The ν th-order modified Bessel function of the second kind is denoted by $K_\nu(\cdot)$, while

$$C(j, n, k) \triangleq \frac{b_1^{\alpha_2-n-1} b_2^{j-k} \beta_1^{\frac{k-n-1-2j}{2}} \beta_2^{\frac{n-k+1-2\alpha_2}{2}}}{k!(j-k)!n!(\alpha_2-n-1)!}. \quad (28)$$

The parameters a, b_1, b_2 depend on the choice of the AF protocol and are given in Proposition 1, while $d \triangleq \kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2$. In the special case of Rayleigh fading ($\alpha_i = 1, \beta_i = \Omega_i$), the OP becomes

$$P_{\text{out}}^{\text{AF,ni}}(x) = 1 - \frac{2e^{-\frac{x}{1-dx}} \left(\frac{b_1}{\Omega_2} + \frac{b_2}{\Omega_1}\right)}{\sqrt{\Omega_1 \Omega_2}} \sqrt{\frac{b_1 b_2 x^2}{(1-dx)^2} + \frac{cx}{(1-dx)}} \times K_1 \left(\frac{2}{\sqrt{\Omega_1 \Omega_2}} \sqrt{\frac{b_1 b_2 x^2}{(1-dx)^2} + \frac{cx}{(1-dx)}}\right) \quad (29)$$

for $x < \frac{1}{d}$ and $P_{\text{out}}^{\text{AF,ni}}(x) = 1$ for $x \geq \frac{1}{d}$.

Proof: This results follows by combining Proposition 1 with Lemma 3 in Appendix A. ■

Theorem 1 generalizes the prior works mentioned above, which all assume ideal hardware. Note that OP expressions equivalent to those in prior works, can be obtained by setting $\kappa_1 = \kappa_2 = 0$ in Theorem 1, which effectively removes the possibility of $x \geq \frac{1}{d}$ since $\frac{1}{d} = \infty$.

Next, closed-form OP expressions for DF relaying are obtained in the general case of non-ideal hardware.

Theorem 2: Suppose ρ_1, ρ_2 are independent and $\rho_i \sim \text{Gamma}(\alpha_i, \beta_i)$ where $\alpha_i \geq 1$ is an integer and $\beta_i > 0$ for $i = 1, 2$. The OP with DF relaying and non-ideal hardware is

$$P_{\text{out}}^{\text{DF,ni}}(x) = 1 - \prod_{i=1}^2 \left(\sum_{j=0}^{\alpha_i-1} \frac{e^{-\frac{N_i x}{P_i \beta_i (1-\kappa_i^2 x)}}}{j!} \left(\frac{N_i x}{P_i \beta_i (1-\kappa_i^2 x)} \right)^j \right) \quad (30)$$

for $x < \frac{1}{\delta}$ where $\delta \triangleq \max(\kappa_1^2, \kappa_2^2)$ and $P_{\text{out}}^{\text{DF,ni}}(x) = 1$ for $x \geq \frac{1}{\delta}$. In the special case of Rayleigh fading ($\alpha_i = 1, \beta_i = \Omega_i$), the OP becomes

$$P_{\text{out}}^{\text{DF,ni}}(x) = \begin{cases} 1 - e^{-\sum_{i=1}^2 \frac{N_i x}{P_i \Omega_i (1-\kappa_i^2 x)}}, & 0 \leq x < \frac{1}{\delta}, \\ 1, & x \geq \frac{1}{\delta}. \end{cases} \quad (31)$$

Proof: By plugging the respective cdfs of Nakagami- m and Rayleigh fading into Proposition 2, we obtain the desired results. ■

We stress that Theorem 2 generalizes the classical results of [33, Eq. (21)] and [2], [34], which were reported for the case of DF relaying with ideal hardware. We also note that Theorem 2 can be straightforwardly extended to multi-hop

relaying scenarios with $M > 2$ hops. The only difference would be to let the index $i \in \{1, \dots, M\}$ account for all M hops.

IV. ERGODIC CAPACITY ANALYSIS

In the case of ergodic channels, the ultimate performance measure is the ergodic channel capacity, expressed in bits/channel use. Similar to [35]–[37], the term *channel* refers to the end-to-end channel with a fixed relaying protocol (e.g., AF or DF). When compared to the ergodic capacity with arbitrary relaying protocols, as in [38], the results for the AF and DF relaying channels should be interpreted as ergodic achievable rates. This section provides tractable bounds and approximations for the ergodic capacities of AF and DF relaying.

A. Capacity of AF Relaying

While the capacity of the AF relaying channel with ideal hardware has been well investigated in prior works (see e.g., [35]–[37] and references therein), the case of AF relaying with hardware impairments has been scarcely addressed. In the latter case, the channel capacity can be expressed as

$$C_{\text{ni}}^{\text{AF}} \triangleq \frac{1}{2} \mathbb{E} \left\{ \log_2 \left(1 + \gamma_{\text{ni}}^{\text{AF}} \right) \right\} \quad (32)$$

where the factor 1/2 accounts for the fact that the entire communication occupies two time slots. The ergodic capacity can be computed by numerical integration, using the fact that the pdf of $\gamma_{\text{ni}}^{\text{AF}}$ can be deduced by differentiating the cdf in Theorem 1. However, an exact evaluation of (32) is tedious, if not impossible, to obtain in closed-form.

To characterize the ergodic capacity of the AF relaying channel with fixed or variable gain, an upper bound is derived by the following theorem.

Theorem 3: For Nakagami- m fading channels, the ergodic capacity $C_{\text{ni}}^{\text{AF}}$ (in bits/channel use) with AF relaying and non-ideal hardware is upper bounded as

$$C_{\text{ni}}^{\text{AF}} \leq \frac{1}{2} \log_2 \left(1 + \frac{\mathcal{J}}{\mathcal{J}d + 1} \right) \quad (33)$$

with

$$\mathcal{J} \triangleq \sum_{n=0}^{\alpha_1} \sum_{k=0}^{\alpha_2} \sum_{m=0}^k \sum_{q=0}^{n+m+2} \frac{(n+1) \beta_1^{\frac{n-m+2-2\alpha_1}{2}} \beta_2^{\frac{m-n-2k}{2}}}{(k-m)!(\alpha_1-n-1)!} \times \frac{\left(\frac{b_1}{b_2}\right)^{\frac{n-m+2+2k}{2}} \left(\frac{c}{b_1}\right)^q}{c(-1)^{\alpha_1+k-q+1}} \left(\frac{c}{q}\right)^q \frac{d^{\alpha_1+k-q+1}}{dt^{\alpha_1+k-q+1}} \left\{ e^{\frac{ct}{2b_1}} \times W_{-\frac{n+m+2}{2}, \frac{n-m+1}{2}} \left(\frac{c}{2b_1} \left(t - \sqrt{t^2 - \frac{4b_1}{b_2 \beta_1 \beta_2}} \right) \right) \times W_{-\frac{n+m+2}{2}, \frac{n-m+1}{2}} \left(\frac{c}{2b_1} \left(t + \sqrt{t^2 - \frac{4b_1}{b_2 \beta_1 \beta_2}} \right) \right) \right\} \Bigg|_{t=\frac{1}{\beta_1} + \frac{b_1}{b_2 \beta_2}} \quad (34)$$

where $W_{\cdot, \cdot}(\cdot)$ denotes the Whittaker W function [39, Ch. 9.22]. The parameters b_1, b_2, c take different values for fixed and variable gain relaying and are given in Proposition 1.

Proof: For brevity, the proof is given in Appendix B. ■

Although the expression in (34) is complicated, we note that analytical expressions for the derivatives of arbitrary order are known for the Whittaker W function [32]; thus, the upper bound in Theorem 3 can be analytically evaluated in an efficient way. For the purpose of numerical illustrations in Section VI, we implemented the upper bound in Theorem 3 using the Symbolic Math Toolbox in MATLAB [40].

Nevertheless, a simpler closed-form expression for the ergodic capacity is achieved by applying the approximation

$$\mathbb{E} \left\{ \log_2 \left(1 + \frac{x}{y} \right) \right\} \approx \log_2 \left(1 + \frac{\mathbb{E}\{x\}}{\mathbb{E}\{y\}} \right) \quad (35)$$

to (32). For Nakagami- m fading channels, we obtain

$$C_{\text{ni}}^{\text{AF}} \approx \frac{1}{2} \log_2 \left(1 + \frac{\alpha_1 \alpha_2 \beta_1 \beta_2}{\alpha_1 \alpha_2 \beta_1 \beta_2 d + \alpha_1 \beta_1 b_1 + \alpha_2 \beta_2 b_2 + c} \right) \quad (36)$$

where the parameters b_1, b_2, c were defined in Proposition 1 for fixed and variable gain relaying. Despite the approximative nature of this result, we show numerically in Section VI that (36) is an upper bound that is almost as tight as the one in Theorem 3. In addition, both expressions are asymptotically exact in the high-SNR regime.

B. Capacity of DF Relaying

Next, we consider the ergodic capacity of the DF relaying channel which is more complicated to analyze than the AF relaying channel; the decoding and re-encoding at the relay gives additional constraints and degrees-of-freedom to take into account [38]. For example, an information symbol must be correctly decoded at the relay before re-encoding, and different symbol lengths and transmit powers can then be allocated to the two hops to account for asymmetric fading/hardware conditions.

For brevity, we consider a strict DF protocol with fixed power and equal time allocation. Based on [38, Eq. (45)], [35, Eq. (11a)], and the effective SNDR expression in (17), the ergodic channel capacity under hardware impairments can be upper bounded as

$$C_{\text{ni}}^{\text{DF}} \leq \min_{i=1,2} \frac{1}{2} \mathbb{E} \left\{ \log_2 \left(1 + \frac{P_i \rho_i}{P_i \rho_i \kappa_i^2 + N_i} \right) \right\}. \quad (37)$$

The intuition behind this expression is that the information that can be sent from the source to the destination is upper bounded by the minimum of the capacities of the individual channels. A closed-form upper bound, which holds for any channel fading distributions, is derived in the new theorem.

Theorem 4: The ergodic capacity $C_{\text{ni}}^{\text{DF}}$ (in bits/channel use) with DF relaying and non-ideal hardware is upper bounded as

$$C_{\text{ni}}^{\text{DF}} \leq \min_{i=1,2} \frac{1}{2} \log_2 \left(1 + \frac{\text{SNR}_i}{\text{SNR}_i \kappa_i^2 + 1} \right). \quad (38)$$

Proof: For brevity, the proof is given in Appendix B. ■

This theorem shows clearly the impact of hardware impairments on the channel capacity: the distortion noise shows up as an interference term that is proportional to the SNR. The upper bound will therefore not grow unboundedly with the SNR, as would be the case for ideal hardware [35], [38]. The next section elaborates further on the high-SNR regime.

V. FUNDAMENTAL LIMITS: ASYMPTOTIC SNR ANALYSIS

To obtain some insights on the fundamental impact of impairments, we now elaborate on the high-SNR regime. Recall the SNR definition, $\text{SNR}_i = \frac{P_i \mathbb{E}\{\rho_i\}}{N_i}$ for $i = 1, 2$, in (9) and the corresponding Remark 1 on the SNR scaling.

For the ease of presentation, we assume that $\text{SNR}_1, \text{SNR}_2$ grow large with $\text{SNR}_1 = \mu \text{SNR}_2$ for some fixed ratio $0 < \mu < \infty$, such that the relay gain remains finite and strictly positive.

Corollary 1: Suppose $\text{SNR}_1, \text{SNR}_2$ grow large with a finite non-zero ratio and consider any independent fading distributions on ρ_1, ρ_2 that are strictly positive (with probability one).

The OP with AF relaying and non-ideal hardware satisfies

$$\lim_{\text{SNR}_1, \text{SNR}_2 \rightarrow \infty} P_{\text{out}}(x) = \begin{cases} 0, & x \leq \frac{1}{\kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2}, \\ 1, & x > \frac{1}{\kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2}, \end{cases} \quad (39)$$

while the OP with DF relaying and non-ideal hardware satisfies

$$\lim_{\text{SNR}_1, \text{SNR}_2 \rightarrow \infty} P_{\text{out}}(x) = \begin{cases} 0, & x \leq \frac{1}{\max(\kappa_1^2, \kappa_2^2)}, \\ 1, & x > \frac{1}{\max(\kappa_1^2, \kappa_2^2)}. \end{cases} \quad (40)$$

Proof: Referring back to (14), observe that we can rewrite the SNDR in terms of $\text{SNR}_1, \text{SNR}_2$ by extracting out the average fading power as $\rho_i = \mathbb{E}_{\rho_i}\{\rho_i\} \tilde{\rho}_i$ (where $\tilde{\rho}_i$ represents a normalized channel gain). By taking the limit $\text{SNR}_1, \text{SNR}_2 \rightarrow \infty$ (with $\text{SNR}_1 = \mu \text{SNR}_2$), we can easily see that the end-to-end SNDR, for variable gain AF relaying, converges to

$$\lim_{\text{SNR}_1, \text{SNR}_2 \rightarrow \infty} \gamma_{\text{ni}}^{\text{AF-v}} = \frac{1}{d} = \frac{1}{\kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2} \quad (41)$$

for any non-zero realization of $\tilde{\rho}_1, \tilde{\rho}_2$. Since this happens with probability one, the OP in (39) is obtained in this case. The proofs for the cases of fixed gain AF relaying and DF relaying follow a similar line of reasoning. ■

A number of conclusions can be drawn from Corollary 1. First, an SNDR ceiling effect appears in the high-SNR regime, which significantly limits the performance of both AF and DF relaying systems. This means that for x smaller than the ceiling, $P_{\text{out}}(x)$ goes to zero with increasing SNR (at the same rate as with ideal hardware; see Section VI) while the OP always equals one for x larger than the ceiling. This phenomenon is fundamentally different from the ideal hardware case, in which an increasing SNR makes the end-to-end SNDR grow without bound and $P_{\text{out}}(x) \rightarrow 0$ for any x . Note that this ceiling effect is independent of the fading distributions of the two hops. Similar behaviors have been observed for two-way relaying in [20], although the exact characterization is different in that configuration.

The SNDR ceiling for dual-hop relaying is

$$\gamma^* \triangleq \begin{cases} \frac{1}{\kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2} & \text{for AF protocol,} \\ \frac{1}{\max(\kappa_1^2, \kappa_2^2)} & \text{for DF protocol,} \end{cases} \quad (42)$$

which is inversely proportional to the squares of κ_1, κ_2 . This validates that transceiver hardware impairments dramatically affect the performance of relaying channels and should be taken into account when evaluating relaying systems. The ceiling is, roughly speaking, twice as large for DF relaying as

for AF relaying;⁸ this implies that the DF protocol can handle practical applications with twice as large SNDR constraints without running into a definitive outage state. Apart from this, the impact of κ_1 and κ_2 on the SNDR ceiling is similar for both relaying protocols, since γ^* is a symmetric function of κ_1, κ_2 .

We now turn our attention to the ergodic capacity in the high-SNR regime. In this case, the following result is of particular importance.

Corollary 2: Suppose $\text{SNR}_1, \text{SNR}_2$ grow large with a finite non-zero ratio and consider any independent fading distributions on ρ_1, ρ_2 that are strictly positive (with probability one).

The ergodic capacity with AF relaying and non-ideal hardware satisfies

$$\lim_{\text{SNR}_1, \text{SNR}_2 \rightarrow \infty} C_{\text{ni}}^{\text{AF}} = \log_2 \left(1 + \frac{1}{\kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2} \right). \quad (43)$$

The ergodic capacity with DF relaying and non-ideal hardware satisfies

$$\lim_{\text{SNR}_1, \text{SNR}_2 \rightarrow \infty} C_{\text{ni}}^{\text{DF}} \leq \log_2 \left(1 + \frac{1}{\max(\kappa_1^2, \kappa_2^2)} \right). \quad (44)$$

Proof: For AF relaying, the instantaneous SNDR is upper bounded as $\gamma_{\text{ni}}^{\text{AF}} \leq \frac{1}{d}$ for any realizations of ρ_1, ρ_2 . The dominated convergence theorem therefore allows us to move the limit in (43) inside the expectation operator of the ergodic capacity expression in (32). The right-hand side of (43) now follows directly from (41). For DF relaying, we see directly from Theorem 4 that $C_{\text{ni}}^{\text{DF}} \leq \min_i \log_2(1 + 1/\kappa_i^2)$, as $\text{SNR}_i \rightarrow \infty$, which gives (44). ■

Similar to the asymptotic OP analysis, Corollary 2 demonstrates the presence of a capacity ceiling in the high-SNR regime. This implies that transceiver hardware impairments make the ergodic capacity saturate, thereby limiting the performance of high-rate systems. Similar capacity ceilings have previously been observed for single-hop multi-antenna systems in [9], [10], [18]. We finally point out that the approximate capacity expression in (36) becomes asymptotically exact and equal to (43), for the case of Nakagami- m fading.

A. Design Guidelines for Relaying Systems

Recall from Lemma 1 that κ_i is the aggregate level of impairments of the i th hop, for $i = 1, 2$. The parameter can be decomposed as

$$\kappa_i = \sqrt{\kappa_{i,t}^2 + \kappa_{i,r}^2} \quad (45)$$

where $\kappa_{i,t}, \kappa_{i,r}$ are the levels of impairments (in terms of EVM) in the transmitter and receiver hardware, respectively. The hardware cost is a decreasing function of the EVMs, because low-cost hardware has lower quality and thus higher EVMs. Hence, it is of practical interest to find the EVM combination that maximizes the performance for a fixed cost.

To provide explicit guidelines, we define the hardware cost as $\sum_{i=1}^2 \zeta(\kappa_{i,t}) + \zeta(\kappa_{i,r})$, where $\zeta(\cdot)$ is a continuously decreasing, twice differentiable, and convex function. The

convexity is motivated by diminishing returns; that is, high-quality hardware is more expensive to improve than low-quality hardware. The following corollary provides insights for hardware design.

Corollary 3: Suppose $\sum_{i=1}^2 \zeta(\kappa_{i,t}) + \zeta(\kappa_{i,r}) = T_{\text{max}}$ for some given cost $T_{\text{max}} \geq 0$. The SNDR ceilings in (42) are both maximized by $\kappa_{1,t} = \kappa_{1,r} = \kappa_{2,t} = \kappa_{2,r} = \zeta^{-1} \left(\frac{T_{\text{max}}}{4} \right)$.

Proof: The proof goes by contradiction. Assume $\kappa_{1,t}^*, \kappa_{1,r}^*, \kappa_{2,t}^*, \kappa_{2,r}^*$ is the optimal solution and that these EVMs are not all equal. The hardware cost is a Schur-convex function (since it is convex and symmetric [41, Proposition 2.7]), thus the alternative solution $\kappa_{1,t} = \kappa_{1,r} = \kappa_{2,t} = \kappa_{2,r} = \frac{\sum_{i=1}^2 \kappa_{i,t}^* + \kappa_{i,r}^*}{4}$ reduces the cost [41, Theorem 2.21]. To show that the alternative solution also improves the SNDR ceilings, we first note that $\kappa_i^2 = \kappa_{i,t}^2 + \kappa_{i,r}^2$ is a Schur-convex function, thus it is maximized by $\kappa_{i,t} = \kappa_{i,r}$ for any fixed value on $\kappa_{i,t} + \kappa_{i,r}$ [41, Theorem 2.21]. In addition, for any fixed value $A = \kappa_1^2 + \kappa_2^2$, γ^* in (42) is maximized by $\kappa_1^2 = \kappa_2^2 = \frac{A}{2}$, which is easily seen from the structure of $\gamma^* = \frac{1}{A + A\kappa_1^2 - \kappa_1^4}$ for AF and $\gamma^* = \frac{1}{\max(\kappa_1^2, A - \kappa_1^2)}$ for DF. The alternative solution decreases cost and increases (42), thus the EVMs must be equal at the optimum. ■

Corollary 3 shows that it is better to have the same level of impairments at every⁹ transceiver chain, than mixing high-quality and low-quality transceiver chains. In particular, this tells us that the relay hardware should ideally be of the same quality as the source and destination hardware.

As a consequence, we provide the following design guidelines on the *highest* level of impairments that can theoretically meet stipulated requirements.

Corollary 4: Consider a relaying system optimized according to Corollary 3. To support a given SNDR threshold, x , it is necessary to have $\kappa_i^2 \leq \sqrt{\frac{1}{x} + 1} - 1$ for AF relaying and $\kappa_i^2 \leq \frac{1}{x}$ for DF relaying for $i = 1, 2$.

Proof: Corollary 3 prescribes that $\kappa_1 = \kappa_2$. Plugging this fact into (42), we obtain equations that give the expressions stated in this corollary. ■

This corollary shows that hardware requirements are looser for DF than for AF, which is also illustrated in Section VI. If the SNDR threshold is substituted as $x = 2^{2R} - 1$, then we achieve the corresponding necessary conditions for achieving an ergodic capacity of R bits/channel use.

Observe that the guidelines in Corollary 4 are necessary, while the sufficiency only holds asymptotically in the high-SNR regime. Thus, practical systems should be more conservatively designed to cope with finite SNRs and different channel fading conditions.

VI. NUMERICAL ILLUSTRATIONS

In this section, the theoretical results are validated by a set of Monte-Carlo simulations. Furthermore, the concepts of SNDR and capacity ceilings and the practical design guidelines of Section V are numerically illustrated.

⁸This is easy to see when κ_1, κ_2 have the same value $\kappa > 0$, which gives $\gamma^* = \frac{1}{\kappa^2}$ for DF relaying and $\gamma^* = \frac{1}{2\kappa^2 + \kappa^4} < \frac{1}{2\kappa^2}$ for AF relaying.

⁹There are four transceiver chains: transmitter hardware at the source, receiver and transmitter hardware at the relay, and receiver hardware at the destination.

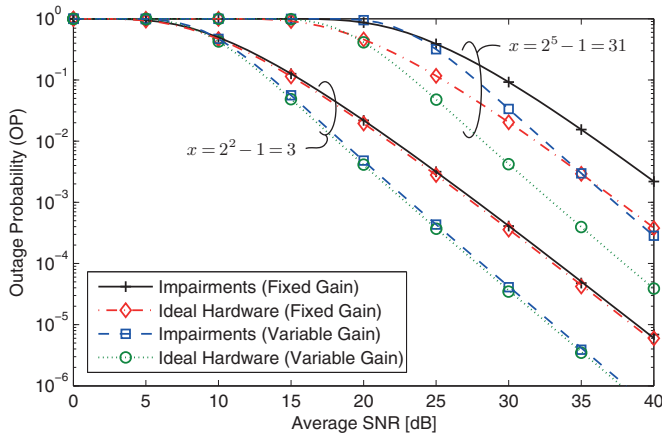


Fig. 2: Outage probability $P_{\text{out}}(x)$ for AF relaying with ideal hardware and with hardware impairments of $\kappa_1 = \kappa_2 = 0.1$.

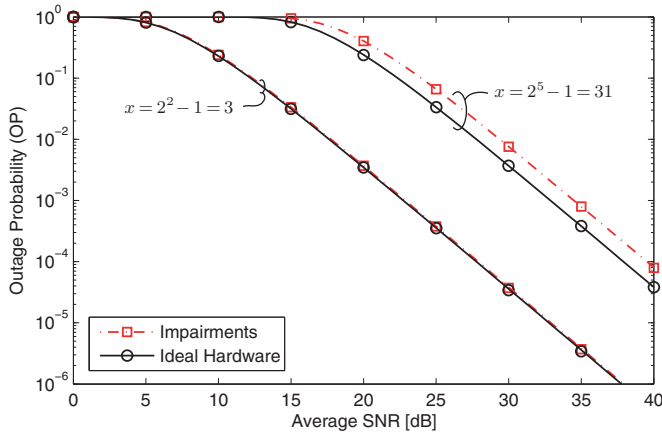


Fig. 3: Outage probability $P_{\text{out}}(x)$ for DF relaying with ideal hardware and with hardware impairments of $\kappa_1 = \kappa_2 = 0.1$.

A. Different Channel Fading Conditions

First, we consider the impact of hardware impairments on the OP, $P_{\text{out}}(x)$, for two different thresholds: $x = 2^2 - 1 = 3$ and $x = 2^5 - 1 = 31$. Keeping in mind that the relay communication occupies two time slots, these correspond to rates of 1 and 2.5 bits/channel use, respectively. We consider a symmetric scenario with fixed levels of impairments of $\kappa_1 = \kappa_2 = 0.1$, independent Nakagami- m fading channels with $\alpha_1 = \alpha_2 = 2$, and the same average SNR at both channels. Recall that the average SNRs are defined in (9) and note that we will not specify $\beta_1, \beta_2, P_1, P_2$ in this section since these parameters are implicitly determined by the average SNR.¹⁰ Increasing the SNR is interpreted as decreasing the propagation distance; see Remark 1.

Fig. 2 and Fig. 3 show the OP as a function of the average SNR for AF and DF relaying, respectively. The curves in Fig. 2 and Fig. 3 were generated by the analytical expressions in Theorems 1 and 2 and show perfect agreement with the marker symbols which are the results of Monte-Carlo

¹⁰Observe that while the shape parameters α_1, α_2 affect the distributions of SNR_1 and SNR_2 , respectively, any selection of the scaling parameter β_i and the transmit power P_i that gives the same value of the product $P_i\beta_i$ will give exactly the same performance and SNR distribution.

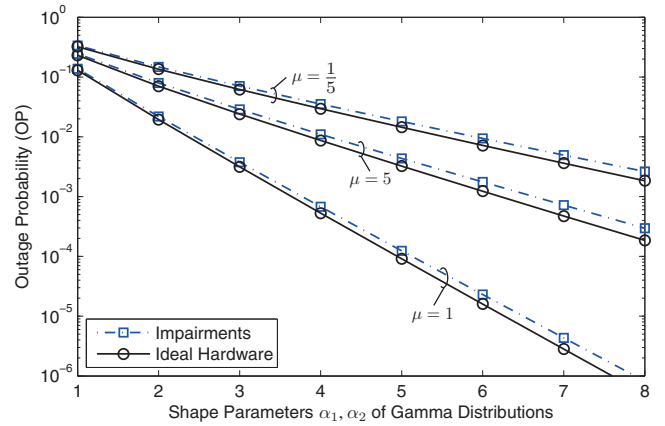


Fig. 4: Outage probability $P_{\text{out}}(3)$ for fixed gain AF relaying with ideal hardware and with hardware impairments of $\kappa_1 = \kappa_2 = 0.1$. Different shape parameters α_1, α_2 are considered in the fading distributions and different asymmetric SNRs: $\text{SNR}_1 = \mu\text{SNR}_2$. The strongest channel has an SNR of 20 dB.

simulations. As shown in these figures, there is only a minor performance loss caused by transceiver hardware impairments in the low threshold case of $x = 3$. However, there is a substantial performance loss when the threshold is increased to $x = 31$. More precisely, AF relaying (with either variable or fixed gain) and DF relaying experience losses of around 5 dB and 2 dB in SNR, respectively, for $x = 31$. The DF protocol is thus more resilient to hardware impairments, which was expected since the distortion noise of the first hop does not carry on to the second hop in this protocol. Nevertheless, the OP curves for AF and DF relaying with non-ideal hardware have the same slope as with ideal hardware; hence, hardware impairments cause merely an SNR offset that is manifested as a curve shifting to the right in Figs. 2 and 3. We also note that variable gain relaying outperforms the fixed one in most scenarios of interest, which is in line with the observations in [3].

Next, we illustrate the impact of the shape parameters α_1, α_2 of the Nakagami- m fading distributions. We also consider different asymmetric setups where $\text{SNR}_1 = \mu\text{SNR}_2$, for $\mu \in \{\frac{1}{5}, 1, 5\}$, while the largest of the SNRs is fixed as $\max(\text{SNR}_1, \text{SNR}_2) = 20$ dB. Fig. 4 shows the OP for $x = 3$ with ideal hardware and with hardware impairments characterized by $\kappa_1 = \kappa_2 = 0.1$. We only show the result for fixed gain AF relaying for brevity. Observe that increasing the shape parameters will monotonically decrease the OP and thus improve the system performance. This is because the variance of the channel gain ρ_i decreases when increasing α_i , while we keep the average SNR fixed. Moreover, we note that it is far better to have the same SNR at both hops than asymmetries. In asymmetric cases, we note from Fig. 4 that it is better to have a strong first hop and a weak second hop than vice versa. This is explained by the amplification of noise in the AF protocol; however, this effect disappears for variable gain AF relaying and DF relaying, which is easily seen from the symmetric SNDR expressions in (14) and (17).

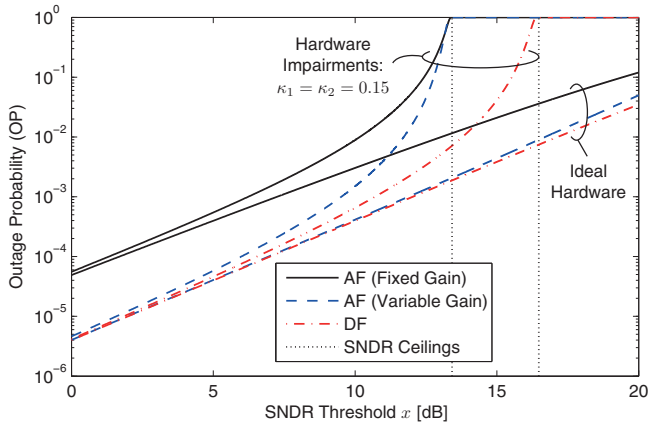


Fig. 5: Outage probability $P_{\text{out}}(x)$ for AF and DF relaying for different thresholds x . As proved in Corollary 1, there exist SNDR ceilings under transceiver hardware impairments.

B. SNDR and Capacity Ceilings

Next, we illustrate the existence of SNDR ceilings. To this end, we consider a fixed average SNR of 30 dB at both channels and independent Nakagami- m fading channels with $\alpha_1 = \alpha_2 = 2$. Fig. 5 shows the OP, $P_{\text{out}}(x)$, as a function of the threshold x (in dB) using either ideal hardware or hardware with impairments of level $\kappa_1 = \kappa_2 = 0.15$. For low thresholds, the OPs for AF (with fixed or variable gain) and DF are only slightly degraded by hardware impairments. The behavior is, however, very different as x increases; the ideal hardware case gives a smooth convergence towards 1, while the practical case of hardware impairments experiences a quick convergence to the respective SNDR ceilings. The value of these ceilings were derived in Corollary 1. As noted earlier, DF relaying is more resilient to hardware impairments and its SNDR ceiling is roughly twice as large as that of AF relaying.

The similar concept of an ergodic capacity ceiling is illustrated in Fig. 6, which shows the capacity of variable gain AF relaying as a function of the average SNR. Both channels are modeled as independent Nakagami- m fading with $\alpha_1 = \alpha_2 = 2$. The capacity is shown for ideal hardware and for hardware with impairments characterized by $\kappa_1 = \kappa_2 \in \{0.05, 0.15\}$. Fig. 6 confirms that hardware impairments have small impact at low SNRs, but are very influential at high SNRs. More precisely, the ergodic capacity saturates and approaches $\log_2(1 + \frac{1}{\kappa_1^2 + \kappa_2^2 + \kappa_1^2 \kappa_2^2})$, as proved by Corollary 2. As the capacity ceiling is determined by the level of impairments, it increases when κ_1, κ_2 are decreased. Fig. 6 also shows the upper capacity bound from Theorem 3 and the simplified capacity approximation from (36). The former gives a somewhat tighter result, but both are asymptotically exact in the high-SNR regime. Although the expression (36) was derived in an approximative manner, we observe that it can indeed be considered as an upper bound on the ergodic capacity and, more importantly, is far easier to evaluate.

C. Design Guidelines

We conclude this section by illustrating some of the guidelines for designing practical relaying systems that were ob-

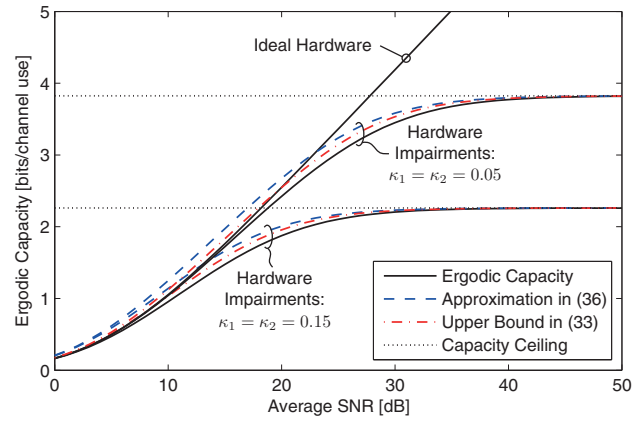


Fig. 6: Exact and approximate ergodic capacity for variable gain AF relaying. As proved in Corollary 2, there exist capacity ceilings under transceiver hardware impairments.

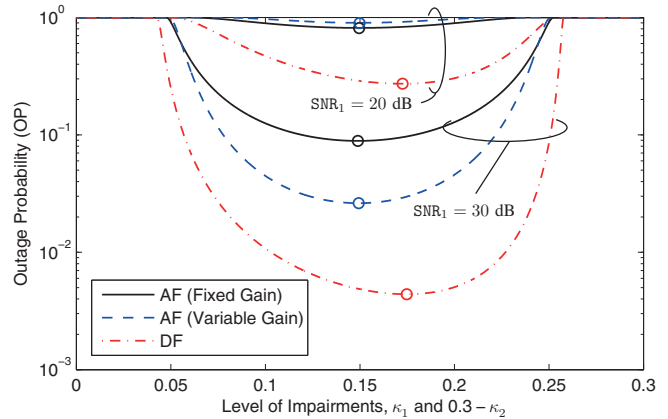


Fig. 7: Outage probability $P_{\text{out}}(15)$ for AF and DF relaying for different levels of impairments κ_1, κ_2 for which $\kappa_1 + \kappa_2 = 0.3$. The minimal value at each curve is marked with a ring.

tained in Section V-A. For simplicity, we set $\zeta(\kappa) = \kappa$ and thus limit the hardware cost by having a total EVM constraint of $\sum_{i=1}^2 \kappa_{i,t} + \kappa_{i,r} = T_{\text{max}}$. Corollary 3 proved that the SNDR ceilings are maximized by setting all κ -parameters equal to $\frac{T_{\text{max}}}{4}$. It is intuitively clear that we should have $\kappa_{1,t} = \kappa_{1,r}$ and $\kappa_{2,t} = \kappa_{2,r}$ (see Lemma 1), but it is less obvious that the aggregate κ -parameters κ_1 and κ_2 should take the same value. To validate this property we consider an asymmetric setup where the first hop is twice as strong: $\text{SNR}_1 = 2\text{SNR}_2$. The channels are modeled as independent Nakagami- m fading with $\alpha_1 = \alpha_2 = 2$.

Fig. 7 shows the OP $P_{\text{out}}(15)$ for two different average SNRs on the first hop: $\text{SNR}_1 \in \{20, 30\}$ dB. The horizontal axis shows the level of impairments of the first hop, κ_1 , while the parameter of the second hop is selected to yield $\kappa_1 + \kappa_2 = 0.3$. Despite the asymmetric SNRs, we observe that the OP with AF relaying (with either fixed or variable gain) is minimized by setting $\kappa_1 = \kappa_2 = \frac{0.3}{2}$. This shows that the design guideline in Corollary 3, which was obtained by high-SNR analysis, can be applied successfully at finite SNRs. We also observe that the OP with DF relaying is minimized

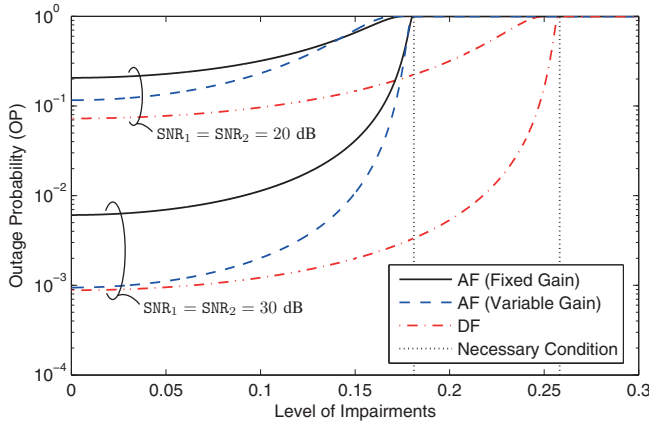


Fig. 8: Outage probability $P_{\text{out}}(15)$ for AF and DF relaying for different symmetric levels of impairments $\kappa_1 = \kappa_2$.

by having a slightly higher hardware quality on the weakest hop than on the strongest hop. This indicates that our general guideline should not be seen as the true optimum, but as a starting point for further adjustments. Furthermore, in the extreme cases when one of the hops is ideal ($\kappa_1 = 0$ or $\kappa_2 = 0$) the system is in full outage; thus, having one ideal hop does not help if the other hop has poor hardware quality.

Based on these insights, we now elaborate on the case with symmetric levels of impairments: $\kappa_1 = \kappa_2$. Suppose our system should operate using $x = 2^4 - 1 = 15$ (i.e., 2 bits/channel use) and we want to achieve a certain value on the outage probability $P_{\text{out}}(15)$. Fig. 8 shows the OPs for AF and DF relaying at two different average SNRs: $\text{SNR}_1 = \text{SNR}_2 \in \{20, 30\}$ dB. Focusing on the 30 dB case and requiring that $P_{\text{out}}(15) \leq 10^{-2}$, we can identify three possible hardware operating regimes from Fig. 8:

- 1) Fixed gain AF relaying with $\kappa_1 = \kappa_2 \leq 0.091$;
- 2) Variable gain AF relaying with $\kappa_1 = \kappa_2 \leq 0.149$;
- 3) DF relaying with $\kappa_1 = \kappa_2 \leq 0.218$.

The different acceptable levels of impairments show that sophisticated protocols (AF with variable gain relaying or, preferably, DF relaying) are more robust to hardware impairments and, thus, can operate with hardware of lower quality. Fig. 8 also shows the necessary conditions of Corollary 4, which act as upper bounds on the level of impairments that can possibly achieve an OP below 1. Although not sufficient, these necessary conditions provide a rough estimate of where the level of impairments must lie.

VII. CONCLUSIONS

Physical transceiver hardware introduces impairments that distort the emitted and received signals in any communication system. While the impact of individual hardware impairments (e.g., phase noise, I/Q imbalance, and HPA non-linearities) have been well investigated in the corresponding literature, it is the aggregate impact of all hardware impairments and the respective compensation algorithms that determine the practical system performance. Motivated by this, we considered a generalized impairment model that has been validated in prior works for single-hop communications and applied it on

flat-fading dual-hop relaying, considering both AF and DF protocols. Our analytical and numerical results manifested that the performance of dual-hop relaying is notably affected by these hardware impairments, particularly when high achievable rates are required. Closed-form expressions for the exact and asymptotic OPs were derived under Nakagami- m fading, along with tractable upper bounds and approximations for the ergodic capacities. These expressions effectively characterize the impact of impairments and demonstrate the existence of fundamental SNDR and capacity ceilings that cannot be crossed by increasing the signal powers or changing the fading conditions. Note that even very small hardware impairments will ultimately limit the performance. These observations also hold true for every individual subcarrier in dual-hop OFDM systems.

We finally derived some useful design guidelines for optimizing the performance of hardware-constrained relaying systems: 1) Use the same hardware quality on all transceivers; 2) Follow the necessary conditions in Corollary 4 to find hardware qualities that can achieve the required system performance; and 3) More sophisticated relaying protocols (e.g., DF) are also more robust to hardware impairments.

APPENDIX A USEFUL LEMMAS

This appendix contains some useful lemmas. The first lemma derives the cdf of SNDR-like expressions and is used to obtain the OPs under Nakagami- m fading.

Lemma 3: Suppose ρ_1, ρ_2 are independent non-negative random variables with cdfs $F_{\rho_i}(\cdot)$ and pdfs $f_{\rho_i}(\cdot)$ for $i = 1, 2$. Let b_1, b_2, c, d be some positive scalars. The random variable

$$\Lambda \triangleq \frac{\rho_1 \rho_2}{\rho_1 \rho_2 d + \rho_1 b_1 + \rho_2 b_2 + c} \quad (46)$$

has a cdf $F_\Lambda(x) = 0$ for $x < 0$, $F_\Lambda(x) = 1$ for $x \geq \frac{1}{d}$, and

$$F_\Lambda(x) = 1 - \int_0^\infty \left(1 - F_{\rho_1} \left(\frac{b_2 x}{(1-dx)} + \frac{b_1 b_2 x^2}{1-dx} + cx \right) \right) f_{\rho_2} \left(z + \frac{b_1 x}{1-dx} \right) dz \quad (47)$$

for $0 \leq x < \frac{1}{d}$. Next, let $\rho_1 \sim \text{Gamma}(\alpha_1, \beta_1)$ and $\rho_2 \sim \text{Gamma}(\alpha_2, \beta_2)$, where α_1, α_2 are strictly positive integers. Then, (47) becomes

$$\begin{aligned} F_\Lambda(x) &= 1 - 2e^{-\frac{x}{1-dx} \left(\frac{b_1}{\beta_2} + \frac{b_2}{\beta_1} \right)} \sum_{j=0}^{\alpha_1-1} \sum_{n=0}^{\alpha_2-1} \sum_{k=0}^j C(j, n, k) \\ &\quad \times \left(\frac{x}{1-dx} \right)^{\alpha_2+j} \left(b_1 b_2 + \frac{c(1-dx)}{x} \right)^{\frac{n+k+1}{2}} \\ &\quad \times K_{n-k+1} \left(2 \sqrt{\frac{b_1 b_2 x^2}{\beta_1 \beta_2 (1-dx)^2} + \frac{cx}{\beta_1 \beta_2 (1-dx)}} \right) \end{aligned} \quad (48)$$

where $K_\nu(\cdot)$ denotes the ν th-order modified Bessel function of the second kind and

$$C(j, n, k) \triangleq \frac{b_1^{\alpha_2-n-1} b_2^{j-k} \beta_1^{\frac{k-n-1-2j}{2}} \beta_2^{\frac{n-k+1-2\alpha_2}{2}}}{k! (j-k)! n! (\alpha_2 - n - 1)!}. \quad (49)$$

Proof: The cdf of Λ is defined as $F_\Lambda(x) = \Pr\{\Lambda \leq x\}$. Since Λ in (46) is a function of both ρ_1 and ρ_2 , we apply the law of total probability to condition on ρ_2 . This gives

$$\begin{aligned} \Pr\{\Lambda \leq x\} &= \int_0^\infty \Pr\{\Lambda \leq x|\rho_2\} f_{\rho_2}(\rho_2) d\rho_2 \\ &= 1 - \int_0^\infty \left(1 - \Pr\{\Lambda \leq x|\rho_2\}\right) f_{\rho_2}(\rho_2) d\rho_2 \\ &= 1 - \begin{cases} \int_0^{\frac{b_1 x}{1-dx}} \left(1 - F_{\rho_1}\left(\frac{(b_2 \rho_2 + c)x}{\rho_2(1-dx) - b_1 x}\right)\right) f_{\rho_2}(\rho_2) d\rho_2, & x < \frac{1}{d}, \\ \int_0^\infty (1 - 1) f_{\rho_2}(\rho_2) d\rho_2 = 0, & x \geq \frac{1}{d}, \end{cases} \end{aligned} \quad (50)$$

where the third equality follows from evaluating the conditional probability $\Pr\{\gamma \leq x|\rho_2\}$ using Lemma 2. This proves that $F_\Lambda(x) = 1$ for $x \geq \frac{1}{d}$. For $x < \frac{1}{d}$, we further note that

$$\begin{aligned} &\int_{\frac{b_1 x}{1-dx}}^\infty \left(1 - F_{\rho_1}\left(\frac{(b_2 \rho_2 + c)x}{\rho_2(1-dx) - b_1 x}\right)\right) f_{\rho_2}(\rho_2) d\rho_2 \\ &\stackrel{(a)}{=} \int_0^\infty \left(1 - F_{\rho_1}\left(\frac{b_2 x}{(1-dx)} + \frac{b_1 b_2 x^2}{z(1-dx)} + cx\right)\right) f_{\rho_2}\left(z + \frac{b_1 x}{1-dx}\right) dz \\ &\stackrel{(b)}{=} \sum_{j=0}^{\alpha_1-1} \frac{e^{-\left(\frac{b_2 x}{\beta_1(1-dx)} + \frac{b_1 x}{\beta_2(1-dx)}\right)}}{j! \beta_1^j \beta_2^{\alpha_2} \Gamma(\alpha_2)} \int_0^\infty \left(\frac{b_2 x}{(1-dx)} + \frac{b_1 b_2 x^2}{z(1-dx)} + cx\right)^j \\ &\quad \times \left(z + \frac{b_1 x}{1-dx}\right)^{\alpha_2-1} e^{-\frac{1}{z}\left(\frac{b_1 b_2 x^2}{\beta_1(1-dx)^2} + \frac{cx}{\beta_1(1-dx)}\right) - \frac{z}{\beta_2}} dz \end{aligned} \quad (51)$$

where (a) follows from a change of variables $z = \rho_2 - \frac{b_1 x}{1-dx}$ and gives (47). Furthermore, (b) follows by plugging in the cdf and pdf from (7)–(8). The remaining integral is of the form in Lemma 4. The final expression in (48) follows from that lemma and some algebraic simplifications. ■

The following lemma summarizes an approach from [32].

Lemma 4: For any constants c_1, c_2, c_3, c_4 with $\Re(c_3) > 0$, $\Re(c_4) > 0$ and some positive integers p_1, p_2 , we have

$$\begin{aligned} &\int_0^\infty (x + c_1)^{p_1} \left(\frac{1}{x} + c_2\right)^{p_2} e^{-\left(\frac{c_3}{z} + zc_4\right)} dx = 2 \sum_{n=0}^{p_1} \sum_{k=0}^{p_2} \binom{p_1}{n} \\ &\quad \times \binom{p_2}{k} c_1^{p_1-n} c_2^{p_2-k} \left(\frac{c_3}{c_4}\right)^{\frac{n-k+1}{2}} K_{n-k+1}(2\sqrt{c_3 c_4}). \end{aligned} \quad (52)$$

Note that $\Re(\cdot)$ denotes the real part of a complex number.

Proof: The binomial formula gives the expansions

$$(x + c_1)^{p_1} = \sum_{n=0}^{p_1} \binom{p_1}{n} x^n c_1^{p_1-n} \quad (53)$$

$$\left(\frac{1}{x} + c_2\right)^{p_2} = \sum_{k=0}^{p_2} \binom{p_2}{k} x^{-k} c_2^{p_2-k} \quad (54)$$

which transform the left-hand side of (52) into

$$\sum_{n=0}^{p_1} \sum_{k=0}^{p_2} \binom{p_1}{n} \binom{p_2}{k} c_1^{p_1-n} c_2^{p_2-k} \int_0^\infty x^{n-k} e^{-\left(\frac{c_3}{z} + zc_4\right)} dx. \quad (55)$$

Finally, (55) is transformed into the right-hand side of (52) by using the integral identity

$$\int_0^\infty x^{n-k} e^{-\left(\frac{c_3}{z} + zc_4\right)} dx = 2 \left(\frac{c_3}{c_4}\right)^{\frac{n-k+1}{2}} K_{n-k+1}(2\sqrt{c_3 c_4}) \quad (56)$$

from [39, Eq. (3.471.9)]. ■

APPENDIX B PROOF OF THEOREMS

Proof of Theorem 3

The end-to-end SNDRs for non-ideal hardware in (13)–(14) are of the form

$$\frac{\rho_1 \rho_2}{\rho_1 \rho_2 d + \rho_1 b_1 + \rho_2 b_2 + c} = \frac{\frac{\rho_1 \rho_2}{\rho_1 b_1 + \rho_2 b_2 + c}}{\frac{\rho_1 \rho_2}{\rho_1 b_1 + \rho_2 b_2 + c} d + 1}. \quad (57)$$

By defining $\psi \triangleq \frac{\rho_1 \rho_2}{\rho_1 b_1 + \rho_2 b_2 + c}$, it means that the ergodic capacity in (32) is of the form $\frac{1}{2} \mathbb{E} \left\{ \log_2 \left(1 + \frac{\psi}{\psi d + 1} \right) \right\}$. We note that the function $\log_2 \left(1 + \frac{\psi}{\psi d + 1} \right)$ is concave of ψ for $\psi \geq 0$, since its second derivative is

$$\frac{-(2d^2 \psi + 2d(\psi + 1) + 1)}{(\log_e(2)(d\psi + 1)^2(d\psi + \psi + 1)^2)} < 0. \quad (58)$$

We can therefore apply Jensen's inequality to obtain

$$C_{\text{ni}}^{\text{AF}} = \frac{1}{2} \mathbb{E} \left\{ \log_2 \left(1 + \frac{\psi}{\psi d + 1} \right) \right\} \leq \frac{1}{2} \log_2 \left(1 + \frac{\mathbb{E}\{\psi\}}{\mathbb{E}\{\psi\}d + 1} \right). \quad (59)$$

Finally, the expectation

$$\mathcal{J} \triangleq \mathbb{E}\{\psi\} = \frac{1}{b_2} \mathbb{E} \left\{ \frac{\rho_1 \rho_2}{\rho_1 \frac{b_1}{b_2} + \rho_2 + \frac{c}{b_2}} \right\} \quad (60)$$

equals (34) by using the moment generating function derived in [32, Theorem 3].¹¹

Proof of Theorem 4

It was shown in the proof of Theorem 3 above that

$$\mathbb{E} \left\{ \log_2 \left(1 + \frac{\psi}{\psi d + 1} \right) \right\} \leq \log_2 \left(1 + \frac{\mathbb{E}\{\psi\}}{\mathbb{E}\{\psi\}d + 1} \right) \quad (61)$$

due to Jensen's inequality and the fact that $\log_2(1 + \frac{\psi}{\psi d + 1})$ is a concave function of ψ for $\psi \geq 0$. In our case, we set $\psi = \frac{P_i \rho_i}{N_i}$, for $i = 1, 2$, thus $\mathbb{E}\{\psi\} = \frac{P_i \mathbb{E}\{\rho_i\}}{N_i} = \text{SNR}_i$. By applying this on each expectation in (37), we obtain (38).

ACKNOWLEDGMENTS

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¹¹We found a typo in [32, Eq. (7)]: the first minus sign in $M_\Lambda(s)$ should be a plus sign. This mistake is also seen in [32, Fig. 3] where the first derivative of $M_\Lambda(s)$ appears to be negative, although it must be positive at $s = 0$ since this represents the mean of a non-negative random variable.

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