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Malyuskin, O., & Fusco, V. (2017). Super-Resolution Defect Characterization Using Microwave Near-Field Resonance Reflectometry and Cross-correlation Image Processing. *Sensing and Imaging*, 18(7).
<https://doi.org/10.1007/s11220-017-0157-8>

Published in:
Sensing and Imaging

Document Version:
Peer reviewed version

Queen's University Belfast - Research Portal:
[Link to publication record in Queen's University Belfast Research Portal](#)

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Super-Resolution Defect Characterization Using Microwave Near-Field Resonance Reflectometry and Cross-correlation Image Processing

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Abstract— A super-resolution defect characterization technique based on near-field resonance reflectometry and cross-correlation image processing is proposed in this paper. The hardware part of the microwave imaging system employs a novel loaded aperture (LA) probe which allows collimation of the electromagnetic field to approximately $\lambda/10$ focal spot(s) at $\lambda/100$ to $\lambda/10$ stand-off distances, λ being the wavelength of radiation in free space. The characteristic raw image spatial resolution of the LA probe is around $\lambda/10$ in one dimension with amplitude contrast/sensitivity exceeding 10-20dB. It is demonstrated that the LA spatial resolution can be at least two times enhanced in two dimensions in the image plane using basic cross-correlation image processing while retaining a very high level of amplitude contrast of at least 10dB.

Keywords: Near-field reflectometry, microwave high-resolution imaging, aperture, electromagnetic field enhancement, measurement, image, correlation.

1. Introduction

Quality control and quality assurance procedures are often based on the comparison of a structure under test with a “standard” test sample. This comparison can be accomplished using optical imaging systems with subsequent image processing, however in many situations optical assessment tools cannot be used due to high cost of equipment and complexity of image processing algorithms. Also, the tested structures can be painted or covered with opaque protective coatings which restrict the application of optical-based quality control methods.

Microwave and millimeter-wave reflectometry [1]- [3] is a proven and widely-accepted imaging tool that permits defect characterization at relatively low cost, with the possibility of operation in both laboratory and industrial environments. Previously, microwave reflectometry has been applied to defectoscopy problems such as detection and evaluation of corrosion under paint and composite laminates [4], [5], fatigue crack detection on metal and dielectric surfaces [6], [7], non-destructive quality assessment of composites [2], etc. The essential part of any reflectometry system responsible for electromagnetic (EM) interaction with the sample and reflected signal

collection is a sensing probe. This can be apertureless [8], [9] or aperture-based [1], [8], [10]. Apertureless probes are commonly represented by open-ended coaxial structures. These probes generate very tight near field pattern with full-width at half-maximum (FWHM) less than $\lambda/10$ at around $\lambda/50$ - $\lambda/100$ standoff distance however electromagnetic coupling of these probes to the sampled material is extremely weak, considerably limiting the image resolution amplitude contrast to less than 1-2dB [8]. The other class of probes is represented by the open-ended waveguide structures or apertures in conductive screens [1], [10]- [13]. The spatial resolution of these probes is limited by the aperture size, which in case of an open ended waveguide probe is approximately $\lambda/4 \times \lambda/2$. As the size of the aperture decreases, the transmitted power reduces, proportionally to the inverse third power of the aperture radius, which considerably limits the imaging distance and reduces the signal-to-noise ratio. Again, near-field coupling of the aperture probes to the sample is weak, resulting in low imaging contrast between the imaged feature(s) and background (typically 1-3dB).

To overcome the limitations of the existing near-field aperture-based microwave probes it has been proposed to employ small apertures in combination with resonance antennas or through the introduction of conductive inserts positioned inside the aperture [14]. Such arrangements [14] lead to high level of EM coupling to the material under test since the dipole insert is parallel to the test surface [15]. The dipole insert can be folded which results in sub-diffraction spatial resolution in two dimensions, [16], [17]. Due to efficient EM coupling the imaging contrast (the contrast between the imaged features and/or the features and the background) can exceed 10-20dB in amplitude and 100 degrees in phase in typical imaging scenarios [14], [16], [17]. Even though other resonance near field reflectometry probes, very small ($\sim\lambda/10$) in all three dimensions have been proposed previously, e.g. a helix antenna [17], the loaded aperture (LA) probe has a number of advantages, including high EM energy localization in the near-field zone. This energy and field localization enables imaging operation with very low power levels (typically as low as -60dBm) or, conversely, allows to achieve highest possible signal-to-noise ratio for a given input power level. At the same time, due to the extended length dimension ($\sim\lambda/4$) of the insert as compared to its width, very high raw image resolution is only possible in the direction orthogonal to the LA length [17]. Additionally, ghost dual-peak image features appear as a result of dipole-mode near field coupling which can be considered as a disadvantage for image interpretation [16]- [18].

In this paper a fundamental possibility to further enhance the spatial resolution of resonance LA probes using image processing techniques based on cross-correlation [17], [19], [20] is demonstrated. It is shown that the application of this image processing to the raw images obtained with the LA probes enables at least two times spatial resolution enhancement (to the resolvable features size $\sim\lambda/25$) in *both dimensions* in the image plane and also eliminates dual-peak features that are present in the raw image. The technique was first proposed in our previous paper [17] and extended here to the case of arbitrary defects of various shape, size and symmetry. This technique is believed to be applicable to a wide range of defect characterization problems, including surface and shallow subsurface diagnostics, and should enhance spatial resolution of any compact near field probe. In this paper consideration is limited to the important practical case of metal-dielectric structures used in printed circuit boards

(PCB) or antenna reflect-arrays [21]. In the present work, the PCB technology allows one to produce test samples and “defect” boards with controllable defects, including size and symmetry deviation for which the performance of the LA reflectometry system is analyzed.

2. Imaging Setup

Fig.1 shows the one-port imaging setup geometry, Fig.1a) and the LA probe detailed view, Fig.1b).

Fig.1.a) Imaging setup geometry; b) detailed view of the loaded aperture probe.

The LA probe is mounted on the planar near-field scanner with scan directions in the xy plane. The sample is held in a vertical position on a wooden frame (not shown in Fig.1). As the probe scans the scene, varying near-field probe-sample EM coupling is transformed into the reflection parameter S_{11} amplitude and phase variation which forms a raw reflection image of the sample under test.

The geometrical parameters of the LA probe, Fig.1b) designed for $\sim 4\text{GHz}$ are summarized in Table 1.

TABLE 1. Dimensions (mm) of the LA probe

d_x	d_y	h_s	L_{sl}	w_{sl}	L_1	L_2	L_3	w_{str}
66	66	3	25	7	18	3	6	2

The aperture is excited by the TE_{10} mode (with E_y component of the EM field) propagating in the open-ended

WR-187 waveguide section with flange dimensions 47.5x22.1 mm, which is fed by a coaxial port, Fig.1a).

The probe generates a dipole-mode transmitted near field pattern, Fig.2a) with the E -field significantly enhanced in the dipole-mode dual hot spots [14], [16], [17]. The probe supports very high-quality transmission resonance around 4.1GHz, Fig.2b).

The near field focusing properties of the LA probe are shown to be in the subwavelength spatial range for imaging distance $z < \lambda/4$ with characteristic FWHM $\sim \lambda/25$ at $\lambda/70$ standoff distance and FWHM $\sim \lambda/7$ at $\lambda/10$ standoff distance. Experiments carried out in [14], [16], [17] demonstrate that in typical imaging scenarios involving dielectric materials and surfaces with conductive elements, the characteristic raw image resolution contrast (defined as variation of the S_{11} parameter from feature to feature or from the feature to background) achievable with the LA probe exceeds 10-20dB in amplitude and 100 degrees in phase of the reflection parameter S_{11} . High image resolution contrast arises as a result of spatial focusing and high-quality EM resonance of the LA probe. At the same time, the characteristic spatial resolution in the raw image is around $\lambda/10$ in the x direction and around $\lambda/4$ in the y direction in the range of standoff distances $\lambda/20$ - $\lambda/8$.

Fig.2.(a) Simulated near E -field amplitude distribution in the xy plane at $z=4\text{mm}$ ($\lambda/20$); (b) measured S_{11} parameter magnitude.

3. Mathematical Model of Defect Characterization in Periodic Printed Arrays Using Cross-Correlation

Image correlation techniques can be used to enhance low-contrast features and detect minute changes in many imaging scenarios [17], [19], [20]. The cross-correlation technique for defect characterization is defined in this paper for comparison between the “master” flawless sample and the “defected” test structure, Fig.3. The technique is applicable to a general range of defectoscopy problems but is studied here only for a specific case of defect characterization in periodic printed antenna arrays.

Fig.3. Correlation-based defect characterization in periodic printed antenna arrays

In the framework of this approach two S_{11} measured data sets are compared: the first set of S_{11} measured data belongs to the “master” board/periodic printed surface without defect and the second set of S_{11} measured data is obtained for the board with a “defect” element, Fig.3. The same measurement grids are used to obtain S_{11} data. It should be noted that instead of experimental data for the master board, simulation data can be used. The correlation-based processing technique is explained in detail below.

First, an auto-correlation function for the “master” board is calculated for each measurement point (x_i, y_j) ,

$$C_M(x_i, y_j) = R_M \cdot R_M^* . \quad (1)$$

In (1) $R_M \equiv R_M(x_i, y_j)$ is a complex-valued reflection coefficient for each measurement point (x_i, y_j) for the “master” board, asterisk symbol denotes complex conjugate. Next the cross-correlation between the “master” and “defect” boards is computed for each measurement point as

$$C(x_i, y_j) = R_M \cdot R_D^* , \quad (2)$$

where $R_D \equiv R_D(x_i, y_j)$ is a complex-valued reflection coefficient for each measurement point for the “defect” board, $i=1,2,...,N_x, j=1,2,...,N_y$ where N_x, N_y are the number of measurement points in x, y directions respectively.

The defect can be characterized by the normalized difference $f_d(x_i, y_j)$ of auto- and cross-correlation functions as

$$f_d(x_i, y_j) = |\Delta C| / C_{\max} \quad (3)$$

where $\Delta C \equiv C_M(x_i, y_j) - C_D(x_i, y_j)$, where $C_{\max} = \max[C_M, C_D]$ is a peak value of the autocorrelation function (1) or an autocorrelation function for the “defect” element $C_D(x_i, y_j) = R_D \cdot R_D^*$. The f_d function can take any value in the range [0,1] with $f_d \rightarrow 1$ for strong defects with large spatial deviation from the “master” element and $f_d \rightarrow 0$ for the flawless sample. It should be noted that in (1)-(3) the defect characterization is achieved using a “local” or point-wise cross-correlation. This technique can be used also in the integral sense by summing (1), (2) over the area of interest, e.g. unit cell. To illustrate the proposed approach, various defects were considered and experimentally characterized, particularly those based on size and symmetry difference between the “master” and “defect” tests.

4. Experimental Defect Characterization and Results Discussion

PCB elements were printed on a 1.6mm thick FR4 substrate without ground plane on the back side. The technique was applied for various standoff distances and measurement steps $\Delta x, \Delta y$. It has been observed that in the range of standoff distances $\lambda/25$ - $\lambda/10$ the imaging resolution deteriorates proportionally to $z^{-1.5}$ where z is an imaging distance [14], [16], [17]. It should be stressed that the measurement step defines the defect resolution and should be of order of the spatial defect deviation [17].

The set of possible defect elements representing typical situations when the defect varies in size, shape or symmetry is shown in Fig.4. The characteristic spatial defect deviation size is $\lambda/20$ - $\lambda/25$.

Fig. 5 shows the printed array geometry, Fig. 5a) and cross-correlation function distribution, Fig. 5b) across the printed antenna array area (300 mm x 240 mm). The array lattice dimensions are 52 mm x 52 mm. The measurement steps are $\Delta x=3.5$ mm, $\Delta y=4.0$ mm. Imaging distance is 5mm and frequency is ~4 GHz. It can be seen that not only defect position can be clearly defined but also the geometry deviation area, encircled by red dotted circles in Fig.5a), is reconstructed. The dual-spot feature present in the near-field pattern of the probe, Fig.2a) is also eliminated.

Fig.4. Set of “defect” elements used for the cross-correlation technique illustration. All dimensions in mm.

Fig.5. (a) Geometry of the board with defect type 1 and (b) cross-correlation function (3) distribution. In the top figure the cross-correlation function maxima corresponding to “defect” element are encircled for reference.

Fig.6. (a) Geometry of the board with defect type 2 and (b) cross-correlation function (3) distribution. In the top figure the cross-correlation function maxima corresponding to “defect” element are encircled for reference.

Fig.6a) shows the printed antenna array containing the “defect” element of type 2, and Fig.6b) shows the f_d function distribution. The antenna array size, cell dimensions and imaging distance and measurement steps are the same as for the printed board in Fig.5a).

Fig.7. (a) Geometry of the board with defect type 3 and (b) cross-correlation function (3) distribution.

It is interesting to note that not only the defect element is detected but also a high cross-correlation level is present for the top row of the printed elements located in the upper left corner of the board. This defect in the top left corner was caused by the “defect” PCB board bow detected by the microwave reflectometer. This defect is unlikely to be detected by an optical system with the optical axis aligned along the normal direction to the PCB board. In the case of the considered board with defect element of type 2, the resolution contrast is ~ 12 dB for the defect size $\sim \lambda/20$.

Finally, Fig.7 demonstrates the printed array geometry (a) and cross-correlation function (b) distribution measured for the printed board with defect of type 3. It can be seen that the defect positions are clearly determined, Fig.7b) with relative contrast 21.4 dB to the average background level. Some asymmetry in the f_d function distribution around the top and bottom parts of the “defect” broken loop is due to relatively coarse measurement step in y direction.

Table 2.

Defect Characterization Based on Cross-Correlation Technique

Defect type	Square lattice dimensions (mm)	Max (f_d)	Average (f_d) outside defect cell
1	52	0.33	0.005
	68	0.30	0.006
2	52	0.14	0.009
	68	0.17	0.006
3	52	0.42	0.003
	68	0.40	0.005

Table 2 summarizes the data for square lattice arrays with lattice (unit cell) dimensions $dx = dy = 52$ mm, represented in Figs.5-7 and sparser arrays with unit cell dimensions $dx = dy = 68$ mm. For example, for the defect of type 1 shown in Fig. 5a) the relative contrast between the peak of the cross-correlation difference function f_d corresponding to encircled “defect” areas and the average background level of f_d outside of the “defect” cell is

$$10 \log \left(\max f_d / \overline{f_d}_{outside} \right) = 10 \log (0.33 / 0.005) = 18.2 \text{ dB} \quad (4)$$

where $\overline{f_d}$ means average value. Therefore, the defects of characteristic size $\sim \lambda/25$ can be very accurately characterized. It is interesting to note that for the bowed PCB in Fig.6 the average background level of f_d outside of the “defect” cell is quite large, 0.009, caused by the above mentioned board deformation.

From data in Table 2 it can be seen that the defects associated with each of the considered defect types, Fig.4 can be very accurately detected and quantitatively characterized with relative contrast to background level better than 12dB. The experimental results obtained with finer imaging step $\Delta x=2.5$ mm, $\Delta y=4.0$ mm show that in general further improvement of the resolution contrast by 1.8-2.5 dB is possible, this however requires longer acquisition times.

5. Conclusions

A high-resolution defect characterization technique based on the resonance focussed microwave reflectometry and image cross-correlation processing is proposed and experimentally evaluated in the case of printed antenna arrays. Experimental results demonstrate that deep subwavelength (characteristic size $\sim \lambda/25$) geometry and symmetry two-dimensional defects can be robustly detected and quantitatively characterized. The defect resolution contrast is defined as the ratio between the maximum of the cross-correlation function corresponding to the defect position and the average level of the cross-correlation function outside the “defect” cell is shown to be from 12 dB to 20 dB for sub-wavelength defects of characteristic size $\lambda/20 - \lambda/25$. The technique should find application in the broad range of surface and sub-surface imaging and defectoscopy scenarios.

6. Acknowledgement

This work was supported in part by the Leverhulme Trust, UK through the Grant RPG-2013-117. The authors would like to thank the anonymous reviewers for their insightful comments and suggestions that allowed them to improve the original manuscript.

7. References

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