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Competition between memory-keeping and memory-erasing decoherence channels

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Titolo nuovo

Tony J. G. Apollaro,^{1,2,3} Salvatore Lorenzo,⁴ Carlo Di Franco,³ Francesco Plastina,^{1,2} and Mauro Paternostro³

¹*Dip. Fisica, Università della Calabria, 87036 Arcavacata di Rende (CS), Italy*

²*INFN - Gruppo collegato di Cosenza, Cosenza Italy*

³*Centre for Theoretical Atomic, Molecular and Optical Physics,*

School of Mathematics and Physics, Queen's University, Belfast BT7 1NN, United Kingdom

⁴*Dipartimento di Fisica e Chimica, Università degli Studi di Palermo, via Archirafi 36, I-90123 Palermo, Italy*

We study the competing effects of simultaneous Markovian and non-Markovian mechanisms acting on a single spin. We show the existence of a threshold in the relative strength of such mechanisms above which the spin dynamics becomes fully Markovian, as revealed by the use of several non-Markovianity measures. We identify a measure-dependent nested structure of such thresholds, hinting at a causality relationship amongst the various non-Markovianity witnesses used in our analysis. Our considerations are then used to argue the unavoidably non-Markovian evolution of a single-electron quantum dot exposed to both intrinsic and Markovian technical noise, the latter of arbitrary strength.

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The dynamics of open quantum systems [1] is of considerable interest both from a fundamental perspective, e.g. for the study of the quantum-to-classical transition [2], and for quantum technology. In the latter context, it is important to understand and characterize the effects that an environment has on the quantum features of a given system [3]. One can distinguish between non-Markovian dynamics, where the coupling with the environment results in the revival of the coherences in the state of the system, and Markovian ones for which no environmental back-action occurs. In many realistic situations, system $\mathcal{S}$ interacts (at different characteristic timescales) with distinct physical environments. This is the case, for instance, for an electron in a quantum dot (QD) that is strongly coupled to the surrounding nuclei and, more weakly, to the phonons of the substrate where it has grown [4], although many other examples can be found.

While even the intuitive picture of a non-Markovian process provided above is not universally agreed on and we lack of a general consensus on the very meaning of memory-keeping dynamics in the quantum realm, some theoretical tools have been recently proposed and used to characterize the degree of the non-Markovian nature in the dynamics of open quantum systems. Measures aiming at quantifying any deviation from a Markovian evolution have been put forward [5–9] and applied to a number of physical situations [10], including the first experiments pointing towards the controlled simulation of non-Markovian dynamics [11].

Notwithstanding a few attempts aimed at finding a unification and an ordering for such a variety of tools [5, 12, 13], and apart from the simple case in which only a *single* decoherence channel is present [14], where all of the previous proposals are essentially equivalent, a conclusive picture has yet to be found. In this work we perform some significant steps in this direction by considering the effects of simultaneous environmental mechanisms. Our aim is to investigate open-system dynamics in the presence of *competing* effects arising because of the simultaneous presence of various channels on a system of interest. On one hand, we will consider the inte-

raction between the system and an environment $\mathcal{E}_{nM}$ that induces strong non-Markovian features. On the other hand, we will assume the system to be exposed also to the influences of a completely forgetful channel $\mathcal{E}_M$ that, on its own, would be responsible for Markovian evolution. Under these conditions, we determine the amount of a “standard white noise” (enforcing a Markovian behavior) that one needs to add to a given memory-keeping channel in order to let it become fully memoryless.

We show that it is possible to identify precise working conditions under which the system evolution changes from Markovian to non-Markovian and viceversa, thus highlighting the way channels of different nature mutually interfere so as to induce a radical change in the character of a dynamics. This is becoming increasingly important in light of schemes that have been recently proposed for quantum state engineering and quantum control based on non-Markovian evolutions [15].

Before entering the core of our analysis, it is beneficial to review shortly the features of the various tools for the analysis of non-Markovianity that have been mentioned above. A common aspect of such measures is that they are expressed in terms of non-Markovianity rates $X_l(t)$ (also termed $\mathcal{N}_l$ -rates in the following, with l a label used to distinguish the various cases that will be addressed below). For Markovian dynamics, these quantities are supposed to stay negative (or constant) in time, while any deviation from negativity signals the non-Markovian nature of an evolution, which is quantified by integrating over the time windows where $X_l(t) > 0$

$$\mathcal{N}_l = \int_{X_l(t) > 0} X_l(t) dt. \quad (1)$$

A few choices for X_l have been made so far [5–8], implying that different *evidences* of non-Markovianity can be gathered from the very same dynamics: The measure proposed in Ref. [5], denoted here as $\mathcal{N}_{BLP}$, is based on the observation that a non-Markovian evolution induces a non-increasing behavior of the state distinguishability. In Ref. [6], some of us proposed to consider $X_{LP} = \partial_t ||F||$, where F is the affine

transformation of the Bloch vector of the system induced by a dynamical map and $\|F\|$ is the absolute value of its determinant. The corresponding measure $\mathcal{N}_{LPP}$ is based on the assumption that a Markovian dynamics induces a monotonic shrinking of the volume of accessible states of $\mathcal{S}$. According to Ref. [7], Markovianity is equivalent to the divisibility of the dynamical map $\Phi_{(t,0)}$ (defined so that $\rho_t^S = \Phi_{(t,0)}\rho_0^S$, where ρ_t^S is the state of the system at time t).

Writing $\Phi_{(t+\tau,0)} = \Phi_{(t+\tau,\tau)} \circ \Phi_{(t,0)}$ with $\circ$ standing for the composition of two maps, Markovianity is mathematically translated into the condition that $\Phi_{(t+\tau,t)}$ should be a completely positive and trace preserving (CPT) map for all t and τ . This implies that one can relate the integrand of $\mathcal{N}_{RHP}$ in Eq. (1) to the deviation from positivity of the Choi matrix (isomorphic to the map $\Phi_{t+\tau,\tau}$). Finally, in Ref. [8] Markovianity is synonymous of monotonic decrease of the mutual information between the system and an ancilla whose joint initial state is maximally entangled.

Let us now consider a system $\mathcal{S}$ interacting with two environments, $\mathcal{E}_M$ and $\mathcal{E}_{nM}$ under the assumption that, if $\mathcal{S}$ interacted only with the former (latter), its dynamics would be Markovian (non-Markovian). In order to fix the ideas, we consider both $\mathcal{S}$ and $\mathcal{E}_{nM}$ embodied by a spin-1/2 particle. The action of the environment $\mathcal{E}_M$ on the state ρ_t of the $\mathcal{S}$ - $\mathcal{E}_{nM}$ system is described by the master equation $\dot{\rho}_t = -i[\hat{\mathcal{H}}, \rho_t] + \mathcal{L}_t \rho_t$, where $\hat{\mathcal{H}}$ is the Hamiltonian describing the $\mathcal{S}$ - $\mathcal{E}_{nM}$ dynamics and $\mathcal{L}_t$ is the Liouville super-operator

$$\mathcal{L}_t \rho_t = \sum_{k,j=1}^3 \frac{\gamma_{kj}}{2} \left([\hat{\sigma}_k^S, \rho_t \hat{\sigma}_j^{S\dagger}] + [\hat{\sigma}_k^S \rho_t, \hat{\sigma}_j^{S\dagger}] \right) \quad (2)$$

that describes the Markovian dynamics that would be enforced by $\mathcal{E}_M$ only. Here, $\hat{\sigma}_j^S$ is the j -Pauli matrix of $\mathcal{S}$ ($j = x, y, z$), and γ_{kj} are the entries of the (hermitian) Kossakowski matrix γ [17]. The dynamical map corresponding to the master equation above is completely positive for $\gamma \geq 0$. In what follows, we will restrict our attention to Kossakowski matrices taking

the form $\gamma = \begin{pmatrix} \gamma_x & \alpha + i\beta & 0 \\ \alpha - i\beta & \gamma_y & 0 \\ 0 & 0 & \gamma_z \end{pmatrix}$. Although this choice does

not embody the most general case, it encompasses several relevant quantum channels [18]. For instance, for $\alpha = \beta = 0$ we have a Pauli channel [19], while an amplitude damping channel is retrieved for $\alpha = \gamma_z = 0$ with $\beta = 2\gamma_{x,y} = \gamma$ [3].

Finally, we take the $\mathcal{S}$ - $\mathcal{E}_{nM}$ interaction to be of the Ising-type, $\hat{\mathcal{H}} = (J/2)\hat{\sigma}_A^z \hat{\sigma}_{nM}^z$. This choice allows us to provide an interesting analysis without introducing unnecessary complications inherent in other coupling models.

The reduced dynamics of $\mathcal{S}$, described by the dynamical map $\rho_t^S = \phi_t(\vec{\gamma}, \alpha, \beta) \rho_0^S$ (with $\rho_t^S = \text{Tr}_{\mathcal{E}_{nM}}[\rho_t]$) is completely characterized by the choice of the entries of γ , here identified by the vector $\vec{\gamma} = (\gamma_x, \gamma_y, \gamma_z)$ and by the parameters α and β . As initial conditions, we consider the factorized state $\rho_0 = \rho_0^S \otimes \rho_0^{\mathcal{E}_{nM}}$ with $\rho_0^S = \begin{pmatrix} A_0^{++} & A_0^{+-} \\ A_0^{-+} & A_0^{--} \end{pmatrix}$ and

$\rho_0^{\mathcal{E}_{nM}} = \begin{pmatrix} B_0^{++} & B_0^{+-} \\ B_0^{-+} & B_0^{--} \end{pmatrix}$, both written in the basis $\{|\pm\rangle\}$ of eigenstates of $\hat{\sigma}_z$. Due to the form of the coupling chosen above, a prominent role will be played by the initial magnetization of $\mathcal{E}_{nM}$. We therefore introduce the parameter $z = 2B_0^{--} - 1$. The evolved state of the system has matrix elements

$$A_t^{++} = \sum_{p=\pm} A_0^{pp} \left(\frac{f_t^p}{2} - \frac{\beta f_t^-}{\gamma_x + \gamma_y} \right), \quad (3)$$

$$A_t^{+-} = A_0^{+-} [\text{Ch} + iJz \text{Sh}] + A_0^{+-} (\gamma_x - \gamma_y - 2i\alpha) \text{Sh}$$

where we have introduced the functions $f_t^\pm = 1 \pm e^{-2(\gamma_x + \gamma_y)t}$ that account for the dissipative action of $\mathcal{E}_M$, and the short-cut notation $\{\text{Ch}, \text{Sh}\} = e^{-(\gamma_x + \gamma_y + 2\gamma_z)t} \{\cosh \xi t, \frac{\sinh \xi t}{\xi}\}$ with $\xi = \sqrt{(\gamma_x - \gamma_y)^2 + 4\alpha^2 - J^2}$. These embody both the decoherence induced by $\mathcal{E}_M$ and the (non-Markovian) dynamics due to the coupling with $\mathcal{E}_{nM}$. The populations of ρ_t^S do not depend on the parameters of $\hat{\mathcal{H}}$ nor on $\rho_0^{\mathcal{E}_{nM}}$ due to the fact that the $\mathcal{S}$ - $\mathcal{E}_{nM}$ coupling is dissipationless. In addition, the coherences are symmetric under the exchange of B_0^{--} with B_0^{++} (or z with $-z$) and viceversa.

With the dynamical map $\phi_t(\vec{\gamma}, \alpha, \beta)$, we can now evaluate some of the measures of non-Markovianity recalled above. Let us start with the isotropic depolarizing channel acting on $\mathcal{S}$. This is set by taking $\gamma_x = \gamma_y = \gamma_z = \gamma_0/4$ and $\alpha, \beta = 0$. In this case, we can provide compact analytical expressions for the $\mathcal{N}$ -rates X_l at the core of Eq. (1) for the four measures discussed above. We find

$$X_{BLP} = \partial_t |G_t|, \quad X_{LPP} = \partial_t [(2f_t - 1)|G_t|^2],$$

$$X_{RHP} = \lim_{\tau \rightarrow 0^+} \frac{1}{2\tau} (g(t, \tau) - f_\tau + |g(t, \tau) - f_\tau|), \quad (4)$$

$$X_{LFS} = \partial_t [2 + 2h(1 - f_t) + \sum_{s=\pm} h(f_t + s|G_t|)],$$

where $h(x) = (x/2) \log_2(x/2)$, $G_t = \sum_{p=\pm} e^{-\gamma_0 t + ipJt} B_0^{pp}$, $f_t = (1 + e^{-\gamma_0 t})/2$, and $g(t, \tau) = |G_{t+\tau}/G_t|$. The dynamics of $\mathcal{S}$ is non-Markovian for any pair (γ_0, z) such that the quantities in Eqs. (4) are non-monotonic. For the N_{RHP} measure, this condition leads to

$$\mu(z, Jt, \gamma_0) \equiv \gamma_0 + \frac{(1 - z^2) \sin(2Jt)}{1 - (1 - z^2) \sin^2(Jt)} < 0. \quad (5)$$

As the function $\mu(z, Jt, \gamma_0)$ is even in z , we can take $z \in (0, 1]$, and obtain $\gamma_{RHP}^* = (1 - z^2)/z$ as a threshold for the onset of Markovianity.

This means that $\mathcal{N}_{RHP} = 0$ and the dynamics is Markovian for all $\gamma_0 \geq \gamma_{RHP}^*$. The case of $z=0$, associated with equal diagonal entries in $\rho_0^{\mathcal{E}_{nM}}$, deserves special attention as in this case $\gamma_{RHP}^* \rightarrow \infty$, implying that the reduced dynamics will always be non-Markovian, regardless of the strength of the coupling between $\mathcal{S}$ and $\mathcal{E}_M$. Following a similar procedure we find the thresholds for the BLP and LPP measures as $\gamma_{BLP}^* = (3/2)\gamma_{LPP}^* = (1 - z^2)/2z$.

Figure 1: (Color online) **(a)** Markovianity phase diagram in the (γ, z) -plane. In the region above (below) each curve, the dynamics of $\mathcal{S}$ is Markovian (non-Markovian) according to the corresponding measure. **(b)** Hierarchy of the time window giving contributions to Eq. (1). In the cases corresponding to the three upper curves, the time evolution is periodic, and positivity intervals recur in time. For the LPS measure, due to lack of periodicity, we only report the first positive interval.

Apart from the thresholds in the decoherence rates, we can also compare the time windows in which the $\mathcal{N}$ -rates are positive and the non-Markovian nature of the dynamics explicitly appears. These are the time intervals effectively contributing to the integral of Eq. (1). For the first three measures these can be cast into the form $\tan t_m^+ \in [y_m^-, y_m^+]$, where $y_m^\pm = (b_m \pm \sqrt{b_m^2 - 4z^2})/2z^2$, m is a label identifying the various measures, and

$$b_{RHP} = 2b_{BLP} = 3b_{LPP} = 2(z^2 - 1)/\gamma. \quad (6)$$

Differently from the other $\mathcal{N}$ -rates, X_{LFS} does not allow for an analytical treatment, and both the threshold for Markovianity onset and the time window have been evaluated numerically, see Fig. (1). It is interesting to notice that for the N_{LFS} measure there is a *critical value* of the rate γ beyond which the evolution of $\mathcal{S}$ is Markovian regardless of the value of z . This feature is unique of such measure, as the remaining ones allow for values of (γ, z) such that the dynamics remains non-Markovian for any γ .

The results presented so far are fully consistent with what is found by using a time-local master equation for the reduced dynamics of $\mathcal{S}$. By following the approach outlined in Ref. [20], this reads

$$\dot{\rho}_t^S = -i[\lambda \hat{\sigma}_z^S, \rho_t^S] + \sum_{i=\pm, z} \Gamma_i(t) \left([\hat{\sigma}_i^S, \rho_t \hat{\sigma}_i^{S\dagger}] + [\hat{\sigma}_i^S \rho_t, \hat{\sigma}_i^{S\dagger}] \right), \quad (7)$$

where we have introduced the ladder operators $\hat{\sigma}_\pm^S = (\hat{\sigma}_x^S \pm i\hat{\sigma}_y^S)/2$, the parameters $\Gamma_\pm(t) = \gamma$ and $\Gamma_z(t) = \frac{1}{2}[\gamma - \frac{(z^2+1)\sin(2Jt)}{1-(1-z^2)\sin^2(Jt)}]$, and the frequency shift λ for the system. The map generated by Eq. (7) is non-Markovian when $\Gamma_z(t) < 0$, which yields the very same threshold as γ_{RHP}^* .

We have thus found a hierarchy of non-Markovianity in the model under study which orders the four measures that we have addressed using the decoherence-rate thresholds

$$\gamma_{RHP}^* \geq \gamma_{BLP}^* \geq \gamma_{LPP}^* \geq \gamma_{LFS}^*. \quad (8)$$

The equalities hold only for $z=1$ [cf. Fig. 1 (a)]. Moreover, as shown in Fig. 1 (b), we have identified a nested structure of the time windows contributing to the integral measures in Eq. (1), showing that

$$t_{LFS}^+ \subset t_{LPP}^+ \subset t_{BLP}^+ \subset t_{RHP}^+. \quad (9)$$

While highlighting in a clear and original way the inherent differences in the various measures that we have considered, each addressing a different facet of non-Markovianity, this result paves the way to the analysis of other dynamical models, in an attempt to establish a universal, model-independent hierarchy. Moreover, all of the measures discussed here share the same extremal behavior w.r.t. the initial population of the non-Markovian environment $\mathcal{E}^{nm}$, i.e., at $z=1$ all measures give zero, whereas at $z=0$ they achieve their maximum values. Remarkably, at this point, the dynamics of $\mathcal{S}$ cannot be made Markovian by adding isotropic depolarizing noise for any value of the decay rate according to three of the measures here employed. On the contrary, the LFS measure gives the threshold $\gamma^* \sim 0.6$ for the onset of Markovian dynamics.

In order to establish a link between the features discussed here and a situation of experimental relevance, we discuss the case of a single electron quantum dot (QD) [4, 21], which, *inter alia*, constitutes one of the most promising platforms for quantum information processing [22, 23]. While the electron constitutes the open system $\mathcal{S}$, the nuclear spins surrounding it might embody an instance of $\mathcal{E}_{nM}$. Moreover, stray phonon excitations due to impurities in the substrate onto which the dot has grown provide an environment that is large enough and sufficiently weakly coupled to $\mathcal{S}$ to be responsible for a Markovian channel [4]. In the following, to fix the ideas, we will refer to the case of a quantum dot in GaAs semiconductor. However, our results are fully general, do not depend on the specific instance of physical system at hand, and can be applied to other similar physical situations.

The logical system states $|\pm\rangle$ used in our analysis are encoded here in admixtures of spin and orbital states of the electron embedded in the QD. The interaction of the electron spin with the nuclear ones is described by the Fermi contact hyperfine Hamiltonian $\hat{\mathcal{H}}_{\mathcal{S}, \mathcal{E}^{nM}} = \sum_{n=1}^N g_n \hat{\sigma} \cdot \hat{\mathbf{I}}^n$, where $I = \frac{3}{2}$ for the $N \simeq 10^5$ nuclear isotopes in the QD. The coupling strength is proportional to the electronic envelop wavefunction $|\psi(\mathbf{r}_n)|^2$ at the n^{th} nuclear position (for more details on the model, see Refs. [24, 25]). Without loss of generality for the purposes of our investigation, we use the so-called box model for the electronic wave function $|\psi(\vec{r}_n)|^2 = 1/V$ (with V the volume occupied by the QD), which implies homogeneous electron-nucleus couplings. We then assume that a strong magnetic field is applied to the QD so that we can legitimately retain the sole longitudinal coupling. By introducing the collective operator $\hat{\mathbf{I}} = g \sum_{n=1}^N \hat{\mathbf{I}}^n$ for the nuclear spins and invoking the rotating-wave approximation, the interaction Hamiltonian takes an Ising-like form $\hat{\mathcal{H}} = \hat{\sigma}^z \hat{\mathbf{I}}^z$ [4, 24]. In the mean-field approach, the fluctuations of the nuclear magnetic field along the z -axis, commonly known as Overhauser field [21], are responsible for the dephasing of the electron-spin state [26]. The

typical timescale for such an effect is $T_2 \simeq 10$ ns as a result of the averaging over many Overhauser field configurations. However, in the presence of strong external magnetic fields and with the application of dynamical-decoupling techniques, $T_2 \simeq 200$ μ s have been achieved experimentally [27]. In the following, we assume such conditions of negligible nuclear-spin-induced dephasing. As an additional remark, we notice that dissipation induced by the relaxation of nuclear spins due to the dipole-dipole interaction (which is not total angular momentum conserving) occurs at much longer timescales [25] so that the electron coupling to the host's phononic background becomes dominant [28].

Within these assumptions, the only environmental effects on the electron spin-orbital states should be ascribed to the phononic bath, which causes fluctuating electrical fields, and to technical noise (fluctuation in the gate potentials, spurious background charges or fabrication defects). In the following we show that, even if these sources of noise could be modelled by Markovian mechanisms, the dynamics of the electron will never be Markovian.

The dynamics of the open system coupled to N mutually non-interacting spins as described above, under the assumption of a general environmental action characterized by the depolarising parameter γ , yields the same map $\rho_t^S = \phi_t \rho_0^S$ reported above. However, here we should take $G_t = e^{-\gamma t} \text{Tr}[e^{-i\hat{I}^z t} \rho^{\mathcal{E}_{NM}}]$, where $\hat{I}^z = \sum_{n=1}^N \hat{I}_n^z$ is the collective nuclear spin operator along the z -axis and $\rho^{\mathcal{E}_{NM}}$ is the density matrix of the N spins that make up $\mathcal{E}_{NM}$. Although this expression can be evaluated for any environmental spin state, here we restrict our attention to the experimentally motivated case of $\rho^{\mathcal{E}_{NM}} = \otimes_{p=1}^N \rho_{nm}^p$. In this case, the single-spin state ρ_{nm}^p is the same regardless of p . These assumptions entail

$$\begin{aligned} \text{Tr}[e^{-i\hat{I}^z t} \rho^{\mathcal{E}_{NM}}] &= \sum_{k=0}^N \binom{N}{k} \frac{e^{-iI^z t(2k-N)}}{2^N} (1+z)^k (1-z)^{N-k} \\ &= [\cos(Jt) + iz \sin(Jt)]^N, \end{aligned} \quad (10)$$

where k is the number of environmental spins in the $|0\rangle$ state. A straightforward calculation shows that the threshold for the onset of Markovian dynamics increases linearly with N as $\gamma_{N_{RHP}}^* = N\gamma_{RHP}^*$, whereas the time intervals at which $\partial_t X > 0$ in Eq. (1) shrinks due to $b_{RHP} = 2N(z^2 - 1)/\gamma$. Considering that, within the range of temperatures typical for quantum dots, $\rho^{\mathcal{E}_{NM}} = (2I+1)^{-N} \mathbb{1}$, i.e., $z=0$, we obtain the remarkable result that the open system dynamics of the dot *cannot* be made Markovian by adding a Markovian noise of whatever rate. In addition, for $N \rightarrow \infty$, we obtain $\mathcal{N}_{RHP} = 1$, $\mathcal{N}_{BLP} = (e^{\pi\gamma} - 1)^{-1}$ and $\mathcal{N}_{LPP} = (e^{3\pi\gamma} - 1)^{-1}$, meaning that the dynamics of $\mathcal{S}$ is non-Markovian for any initial state of $\mathcal{E}_{nm}$ that is not an eigenstate of $\hat{I}^z$. As seen above, for $z=1$ the reduced dynamics is Markovian regardless of γ and N .

We have investigated the behavior of the open-system dynamics of a spin- $\frac{1}{2}$ subject to the competing action of Markovian and non-Markovian environments, identifying the conditions

under which the system evolution becomes Markovian. These account in well defined thresholds in the relative strength of the coupling of the system to the various environments. A nested hierarchical structure then results for the measures of non-Markovianity that we have considered, which suggests a causality relation amongst the different physical phenomena used to characterize non-Markovianity in this context. Our findings might be used to acquire information on the open-system dynamics of a single-electron QD for which, under fairly reasonable assumptions, a Markovian description of the dynamics turns out to be fully inadequate.

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Appendix: analysis of other decoherence channels

In this Appendix we extend the analysis presented in the main text to the case of a more general decoherence channel given by a combination of an amplitude damping and a depolarizing ones. The resulting channel is characterized by the Kossakowski matrix

$$\gamma = \begin{pmatrix} \gamma_A & i\gamma_A/2 & 0 \\ -i\gamma_A/2 & \gamma_A & 0 \\ 0 & 0 & 0 \end{pmatrix} + \begin{pmatrix} \gamma_D & 0 & 0 \\ 0 & \gamma_D & 0 \\ 0 & 0 & \gamma_D \end{pmatrix}. \quad (11)$$

The case $\gamma_A = 0$ has been already analyzed in the main text. In the presence of the amplitude damping component, the explicit expressions for the $\mathcal{N}$ -rates are analogous to the ones reported in the main text in Eq. (4). By introducing $f_t^\pm = 1 \pm e^{-4(\gamma_A + \gamma_D)t}$ we have

$$\begin{aligned} X_{BLP} &= \partial_t |G_t|, \\ X_{LPP} &= \partial_t [(f_t^+ - 1)|G_t|^2], \\ X_{RHP} &= \lim_{\tau \rightarrow 0^+} \frac{1}{2\tau} \left(g(t, \tau) - \frac{f_\tau^+}{2} + \left| g(t, \tau) - \frac{f_\tau^+}{2} \right| \right), \\ X_{LFS} &= \partial_t \mathcal{I}(\sigma), \end{aligned} \quad (12)$$

where $\mathcal{I}(\sigma)$ stands for the Quantum mutual information of the matrix

$$\sigma = \frac{1}{4} \begin{pmatrix} f_t^+ - \frac{\gamma}{2} f_t^- & 0 & 0 & 2G_t^* \\ 0 & f_t^- - \frac{\gamma}{2} f_t^+ & 0 & 0 \\ 0 & 0 & f_t^- + \frac{\gamma}{2} f_t^+ & 0 \\ 2G_t & 0 & 0 & f_t^+ + \frac{\gamma}{2} f_t^- \end{pmatrix}, \quad (13)$$

Figura 2: (Color online) Markovianity phase diagram in the (γ_A, γ_D) plane, with $z = 0.5$ (other values of the initial magnetization for $\mathcal{E}_{nM}$ give rise to similar behaviors). The dynamics of the system is Markovian within the colored regions according to the various non-Markovianity measures. The borders of these regions (pointed by the arrows) represent the threshold conditions discussed in the text. The LFS measure has a different behavior for small γ_A , while it tends to coincide with the others quantifiers when the rate of the amplitude damping channel gets larger.

where we have introduced the parameters

$$\Upsilon = \frac{\gamma_A}{(\gamma_A + \gamma_D)}, \quad G_t = \sum_{p=\pm} e^{-2(\gamma_A + 2\gamma_D)t + ipJt} B_0^{pp},$$

$$g(t, \tau) = \sqrt{\left(\frac{\beta}{4} f_\tau\right)^2 + \left|\frac{G_{t+\tau}}{G_t}\right|^2}. \quad (14)$$

The dynamics of $\mathcal{S}$ turns out to be non-Markovian for any triplet γ_A, γ_D, z such that the quantities in Eqs. (4) are positive. For the $\mathcal{N}_{RHP}$ measure, this condition leads to the inequality

$$4\gamma_D - \frac{(z^2 - 1) \sin(2Jt)}{\cos^2(Jt) + z^2 \sin^2(Jt)} < 0. \quad (15)$$

As this function does not depend on γ_A , this implies that a Markovian behavior occurs for decoherence rates satisfying the same threshold valid for the sole depolarizing channel.

For the $\mathcal{N}_{BLP}$ and the $\mathcal{N}_{LPP}$ measures, on the other hand, the positivity condition leads to

$$4(\gamma_A + m\gamma_D) + \frac{(1 - z^2) \sin(2Jt)}{\cos^2(Jt) + z^2 \sin^2(Jt)} < 0, \quad (16)$$

with $m = 2$ ($m = 3$) for the BLP (LPP) measure. For the BLP case, the onset of Markovian dynamics is found to occur for $\gamma_A + 2\gamma_D = (1 - z^2)/2z$, while the analogous condition for the LPP measure reads $2\gamma_A + 3\gamma_D = (1 - z^2)/3z$. The form taken by the LFS measure does not allow for an analytic expression. Its behavior is shown in Fig. 2 as a function of γ_A and γ_D , at a set value of z , and is compared to the BLP and LPP measures so as to establish a Markovianity phase-diagram valid for the respective measure.

A hierarchical relation among the time windows that contribute to the evaluation of the different indicators can be found here too and leads precisely to the structure given in Eq. (9).

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