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Roche tomography of cataclysmic variables – IV. Star-spots and slingshot prominences on BV Cen

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ABSTRACT
We present Roche tomograms of the G5–G8 IV/V secondary star in the long-period cataclysmic variable BV Cen reconstructed from Magellan Inamori Kyocera Echelle spectrograph echelle data taken on the Magellan Clay 6.5-m telescope. The tomograms show the presence of a number of large, cool star-spots on BV Cen for the first time. In particular, we find a large high-latitude spot which is deflected from the rotational axis in the same direction as seen on the K3–K5 IV/V secondary star in the cataclysmic variable AE Aqr. BV Cen also shows a similar relative paucity of spots at latitudes between 40° and 50° when compared with AE Aqr. Furthermore, we find evidence for an increased spot coverage around longitudes facing the white dwarf which supports models invoking star-spots at the L1 point to explain the low states observed in some cataclysmic variables. In total, we estimate that some 25 per cent of the Northern hemisphere of BV Cen is spotted.

We also find evidence for a faint, narrow, transient emission line with characteristics reminiscent of the peculiar low-velocity emission features observed in some outbursting dwarf novae. We interpret this feature as a slingshot prominence from the secondary star and derive a maximum source size of 75 000 km and a minimum altitude of 160 000 km above the orbital plane for the prominence.

The entropy landscape technique was applied to determine the system parameters of BV Cen. We find $M_1 = 1.18 \pm 0.16 M_\odot$ and $M_2 = 1.05 \pm 0.13 M_\odot$ and an orbital inclination of $i = 53^\circ \pm 4^\circ$ at an optimal systemic velocity of $\gamma = -22.3 \text{ km s}^{-1}$. Finally, we also report on the previously unknown binarity of the G5IV star HD 220492.

Key words: techniques: spectroscopic – stars: imaging – stars: individual: BV Cen – stars: late-type – novae, cataclysmic variables – stars: spots.

1 INTRODUCTION
Cataclysmic variables (CVs) are short-period binary systems in which a (typically) late main-sequence star (the secondary) transfers material via Roche lobe overflow to a white dwarf primary star. For an excellent review of CVs, see Warner (1995). Although CVs are largely observed to study the fundamental astrophysical process of accretion, it is the Roche lobe filling secondary stars themselves that are key to our understanding of the origin, evolution and behaviour of this class of interacting binaries.

In particular, the magnetic field of the secondary star is thought to play a crucial role in the evolution of CVs – driving CVs to shorter orbital periods through magnetic braking (e.g. Kraft 1967; Mestel 1968; Rappaport et al. 1983; Spruit & Ritter 1983). Furthermore, the transition of the secondary star to a fully convective state and the supposed shutdown of magnetic activity that this transition brings is also invoked to explain the period gap – the dearth of CVs with orbital periods between $\sim 2–3$ h. On more immediate time-scales, magnetic activity on the secondary stars is also thought to explain variations in CV orbital periods, mean brightness, mean outburst durations and outburst shapes (e.g. Bianchini 1990; Richman, Applegate & Patterson 1994; Ak, Ozkan & Mattei 2001).

That the secondary star and its magnetic field should have such a large and wide-ranging impact on CV properties should come as no surprise – the secondary star essentially acts as the fuel reserve that powers these binaries. Therefore, an understanding of the magnetic field properties of the secondary stars in CVs (e.g. spot sizes, distributions and their variation with time) is crucial if we are to understand the behaviour of these binaries. In addition, detailed studies of the rapidly rotating secondary stars in CVs can also provide tests...
of stellar dynamo theories under extreme conditions. For example, questions regarding the impact of tidal forces on magnetic flux tube emergence (e.g. Holzwarth & Schlüller 2003) and its effect on differential rotation (e.g. Schärlemann 1982) are particularly pertinent (see Watson, Dhillon & Shabaz 2006, for a discussion).

Despite this, until recently there had been little direct observational evidence for magnetic activity in CVs. Webb, Naylor & Jeffries (2002) used TiO bands to infer the presence of spots on the secondary star in SS Cyg and estimated a spot filling factor of 22 per cent. Unfortunately, this technique does not allow the surfaces of these stars to be imaged and hence the spot distributions could not be ascertained.

Most recently, Watson et al. (2006) used Roche tomography to map the star-spot distribution on a CV secondary (AE Aqr) for the first time. In Watson et al. (2006), we estimated that star-spots covered approximately 18 per cent of the Northern hemisphere of AE Aqr. The Roche tomogram of AE Aqr also showed that star-spots were found at almost all latitudes, although there was a relative paucity of star-spots at a latitude of ~40°. Furthermore, we found that, in common with Doppler images of single rapidly rotating stars, AE Aqr also displayed a large high-latitude spot. In this work, we continue with our series of papers on Roche tomography (see Watson & Dhillon 2001; Watson et al. 2003, 2006) by mapping starspots on the long-period (0.61-d) dwarf nova BV Cen for the first time. We also report on the serendipitous discovery of the binarity of HD 220492.

2 OBSERVATIONS AND REDUCTION

Simultaneous spectroscopic and photometric observations were carried out over three nights on 2004 July 8–10. The spectroscopic data were acquired using the 6.5-m Magellan Clay Telescope and the simultaneous photometry was carried out using the Carnegie Institution’s Henrietta Swope 1.0-m Telescope. Both telescopes are situated at the Las Campanas Observatory in Chile.

2.1 Spectroscopy

The spectroscopic observations of BV Cen were carried out using the dual-beam Magellan Inamori Kyocera Echelle spectrograph (MIKE – see Bernstein et al. 2003). The MIT Lincoln Labs CCD-20 chip with 2046 × 4096 pixel was used in the blue channel, and the SITE ST-002A chip, again with 2046 × 4096 pixel, was used in the red channel. The standard set-up was used, allowing a wavelength coverage of 3330–5070 Å in the blue arm and 4460–7270 Å in the red arm, with significant wavelength overlap between adjacent orders. With a slitwidth of 0.7 arcsec, a spectral resolution of around 38 100 (~7.8 km s⁻¹) and 31 500 (~9.5 km s⁻¹) was obtained in the blue and red channels, respectively. The chips were binned 2 × 2 resulting in a resolution element of ~2.3 binned pixels in the red arm and 2.6 binned pixels in the blue arm for our chosen slit. The spectra were taken using 400-s exposure times in order to minimize velocity smearing of the data due to the orbital motion of the secondary star. Comparison Th–Ar arc lamp exposures were taken every ~50 min for the purposes of wavelength calibration.

With this set-up, we obtained 63 usable spectra in each arm. Since the main goal of the Magellan run was to observe AE Aqr, we were restricted to 3-h windows each night to observe BV Cen. Over our allocated four nights, this would have allowed over 80 per cent of the orbit of BV Cen to be observed, but unfortunately we lost the final night due to bad weather. Other than that, the seeing was typically 0.6–0.7 arcsec on the first night and 0.9 arcsec on the next two nights, with occasional degradation to 1.5 arcsec. The peak signal-to-noise ratio (S/N) of the blue spectra ranged from 29 to 56 (typically ~50) in the blue arm, and from 38 to 76 (typically ~65) in the red arm. Table 1 gives a journal of the observations.

It should be noted that when using MIKE it is not possible to change the slit orientation on the sky. In order to compensate for this, and reduce atmospheric dispersion across the slit, MIKE is mounted at a 30° angle to the Naysmith platform. This means that at zenith distances greater than ~50° dispersion across the slit becomes significant. To avoid this, all observations of BV Cen were carried out at low airmasses and no exposure of BV Cen was carried out for an airmass above 1.39 (zenith distance >44°).

2.1.1 Data reduction

The data were reduced using the MIKE REDUX IDL pipeline version 1.7. This automatically processes all calibration frames and then wavelength calibrates, sky subtracts, flux calibrates and optimally extracts the target frames. The final output consists of 1D spectra for the blue and red arms. The typical rms scatter reported for the wavelength calibration was around 0.002 Å. Since the REDUX package outputs vacuum wavelengths, whereas the line-lists used in the least-squares deconvolution (LSD) process (see Section 3) are...
measured in air, the wavelengths have been converted to air using the IAU standard given by Morton (1991).

Unfortunately, we experienced some flux calibration problems around regions of strong emission lines (e.g. Hα and Hβ), most likely due to poor tabulation of our flux standard star HR 5501 around these lines. Since we mask out the strong emission lines during our study of the donor star absorption lines, this problem does not affect this work. We also found that we could not resolve (at the data-reduction stage) a small jump in the flux level between the blue and red arms. We discuss the solution to the latter problem in Section 3.

Since the secondary star contributes a variable amount to the total light of a CV, Roche tomography is forced to use relative line fluxes during the mapping process (i.e. it is not possible to employ the usual method of normalizing the data). In order to determine these relative fluxes, the slit losses need to be calibrated. The standard technique of using a comparison star on the slit is, however, not possible with MIKE due to the tightly packed, cross-dispersed format, and so simultaneous photometry is required (see Section 2.2). We corrected for slit losses by dividing each BV Cen spectrum by the ratio of the flux in the spectrum (after integrating the spectrum over the appropriate photometric filter response function) to the corresponding photometric flux (see Section 2.2). We should note here that the slit-loss correction factors were only calculated using the red spectra, but applied to both arms of the spectroscopic data. A further correction was applied to the blue arm (to account for both a different slit-loss factor in the blue compared to the red and also the jump in flux level between the two arms mentioned earlier) at the LSD stage (see Section 3).

2.2 Photometry

Simultaneous photometric observations were carried out using a Harris V-band filter and the Site3 CCD chip with 2048 × 3150 pixel. The CCD chip was windowed to a size of 633 × 601 pixel (which covered the target and the brightest comparison stars, as well as the bias strip) resulting in a 4 × 4-arcmin² window on the sky. Windowing allowed the readout time to be reduced to 46 s for each 15-s exposure on BV Cen.

2.2.1 Data reduction

The photometry was reduced using standard techniques. Since the master bias-frame showed no ramp or large-scale structures across the chip, the bias level of the frames was removed by subtracting the median of the pixels in the overscan regions. Pixel-to-pixel sensitivity variations were then corrected for by dividing the target frames by a master twilight flat-field frame. Optimal photometry was performed using the package PHOTOM (Eaton, Draper & Allen 2002). There were two suitable comparison stars on each BV Cen target frame, identified from the ESO Guide Star Catalogue as GSC0866601471 (hereafter 1471) and GSC0866600859 (hereafter 0859). Two other bright stars in the field were deemed unsuitable since one was overexposed, and the other had a nearby companion. Unfortunately, neither of the comparisons had reliable magnitude measurements available. We therefore used observations of the Landolt photometric standard SA105–437 to calibrate our instrumental magnitudes. This allowed us to determine the magnitude of 1471 and 0859 as $m_V = 13.43 \pm 0.07$ and $13.54 \pm 0.07$, respectively. Finally, differential photometry was performed using the bright nearby comparison star 1471. The light curve is shown in Fig. 1.

2.3 Continuum fitting

The continuum of the BV Cen spectra was fitted in exactly the same manner as that outlined in the Roche tomography study of AE Aqr (Watson et al. 2006). Spline knots were placed at locations in the spectra that were relatively line-free. The spline knot positions were chosen on an individual spectrum-by-spectrum basis (though the locations of the knots were generally the same for each spectrum) until a smooth and visually acceptable fit was obtained. Again, as in Watson et al. (2006), we found that we systematically fit the continuum at too high a level, leading to continuum regions in the LSD (see Section 3) profiles lying below zero. The continuum fit was then shifted to lower levels until the continuum levels in the LSD profiles lay at zero. The exact value of this shift varied from spectrum to spectrum, due to changes in the continuum shape as a result of variable accretion light, but the variation was generally small. We found that this process did not change the actual LSD profile shape.

3 LEAST-SQUARES DECONVOLUTION

LSD effectively stacks approximately thousands of photospheric absorption lines observable in a single echelle spectrum to produce a ‘mean’ profile of greatly increased S/N. The technique of LSD is well documented and was first applied by Donati et al. (1997) and has since been used in many Doppler imaging studies (e.g. Barnes et al. 1998; Lister, Collier Cameron & Barutis 1999; Barnes et al. 2000, 2001; Jeffers, Barnes & Collier Cameron 2002; Barnes et al. 2004; Marsden et al. 2005) as well as in the successful mapping of star-spots on AE Aqr (Watson et al. 2006). For detailed information on LSD, see these references as well as the review by Collier Cameron (2001).

At present we use line-lists generated by the Vienna Atomic Line Data base (VALD – Kupka et al. 1999, 2000) for LSD. The spectral type of the secondary star in BV Cen has been determined to lie within the range G5–G8 IV/V (Vogt & Breyerscher 1980). In our analysis (see Section 5), later-type spectral templates appear to fit the BV Cen spectra better, with our closest match being a G8IV template. In accordance with this, we downloaded a line-list for a stellar atmosphere with $T_{\text{eff}} = 5250$ K and $g = 3.55$ (the closest approximation available in the data base to a G8IV spectral type). We do not consider a slight error in the choice of the line-list used as having a significant impact on the results of the LSD process – see

Figure 1. The V-band light curve of BV Cen. The data have been phased according to the ephemeris derived in Section 5. All three nights’ data have been plotted together from phases 0 and 1.
Since the green spectra were slit-loss corrected using simultaneous photometry, the resulting LSD profiles from the green data are scaled correctly relative to one another. We then rebinned the blue LSD profiles to the same velocity scale as that of the red profiles (since the blue arm had a superior resolution) using sinc-function interpolation. Slit-loss corrections to the blue LSD profiles were then made by scaling the blue LSD profiles to match the red profiles obtained at the same phase. This scaling was done using an optimal subtraction algorithm. The blue profiles were scaled by a factor $f$ and then subtracted from the red profile. The factor $f$ that resulted in the minimum scatter in the residuals (compared to a smoothed version of the residuals) was then used to scale the blue LSD profiles. This method allowed the slit-losses in the blue to be calibrated despite the jump in flux between the red and blue arms. In addition, this method also allows further loss of light in the blue due to differential refraction to be corrected to first order. Deconvolving the blue and red data separately also allowed us to look for systematic problems and/or differences in the profiles, of which none was apparent. We should note, however, that the LSD profiles exhibit a slight tilt, with the red continuum (more positive velocities) systematically higher than the continuum on the other side of the profile. This is a well-known artefact (e.g. Barnes 1999) which will have little impact on the final image reconstruction.

The individual LSD profiles are shown in Fig. 2. These clearly show the distinct emission bumps due to star-spots moving from blue (negative velocities) to red (positive velocities) through the profile as BV Cen rotates. When the LSD profiles are trailed (Fig. 3), these features are still obvious in addition to the secondary stars’ orbital motion and variations in the projected equatorial velocity, $v \sin i$. Fig. 3 also shows the trailed LSD profiles after removal of the orbital motion and subtraction of a theoretical profile at each phase. The theoretical profiles were calculated using our Roche tomography code by adopting the binary parameters and limb-darkening described in Section 6 and a featureless stellar disc. This process increases the contrast and enhances the star-spot signatures (which now appear dark).

4 ROCHE TOMOGRAPHY

Roche tomography is analogous to Doppler imaging (e.g. Vogt & Penrod 1983) and has now been successfully applied to the donor stars of CVs on several occasions (Rutten & Dhillon 1994, 1996; Watson et al. 2003; Schwope et al. 2004; Watson et al. 2006). Rather than repeating a detailed description of the methodology and axioms of Roche Tomography here, we refer the reader to the references...
Figure 3. Left-hand panel: a trail of the deconvolved profiles of BV Cen. The large gaps are due to non-continuous observations over three nights. The small gaps in the phase coverage are at times when arc spectra were taken for the purpose of wavelength-calibration. Features due to star-spots appear bright and several such features are clearly visible traversing the profiles from blue (more negative velocities) to red (more positive velocities) in the trailed spectra. Also evident are the orbital motion and variation in $v \sin i$, which show a maximum at phase 0.75 due to the varying aspect of the tidally distorted secondary star. Right-hand panel: the same as the left-hand panel, except the orbital motion has been removed using the binary parameters derived in Section 6. This allows the star-spot tracks across the profiles to be more easily followed. In order to increase the contrast of this plot, we have subtracted a theoretical profile (see the text) from each LSD profile before trailing. Features due to star-spots and irradiation appear dark in these plots. Note the narrow feature (indicated with an arrow and shown enlarged – see the inset) that lies outside the blue edge of the profiles at phases 0.328–0.366, which seems to follow the motion of the large feature that runs through the profiles during this block of observations. This feature is discussed in more detail in Section 8.

above and the technical reviews of Roche Tomography by Watson & Dhillon (2001), Dhillon & Watson (2001) and Watson & Dhillon (2004). The pertinent points with respect to this work are that we employ a moving uniform default map, where each element is set to the average value of the reconstructed map. Furthermore, we do not adopt a two-temperature or filling factor model (e.g. Collier Cameron & Unruh 1994), since these assume only two temperature components across the star while CV donors are expected to exhibit large temperature differences due to the impact of irradiation. This means our Roche tomograms may be prone to the growth of bright pixels (which two-temperature models suppress, Collier Cameron 1992) and are quantitatively more difficult to analyse.

5 EPHemeris

Despite the brightness of BV Cen, and the fact that it is one of the longest-period dwarf novae known, the system has been poorly studied. The most-recent orbital ephemeris for BV Cen was published by Gilliland (1982) and will have accumulated a large error over the last two decades. We have therefore determined a new ephemeris for BV Cen by cross-correlation with suitable template stars that were observed using the same instrumental set-up. The cross-correlation was carried out over the spectral range 6400–6536 Å. This wavelength range not only covers several moderately strong lines and blends from the secondary that are useful for radial velocity measurements but also includes several temperature- and gravity-sensitive lines for F–K stars (Strassmeier & Fekel 1990).

The BV Cen and template spectra were first rebinned on to the same velocity scale using sinc-function interpolation and then normalized by dividing by a constant. The continuum was then subtracted by a third-order polynomial fit. This procedure is followed to ensure that the line-strengths are preserved across the spectral region of interest. The template spectra were then broadened to account for the rotational velocity ($v \sin i$) of the secondary star — the amount of broadening applied was determined using an optimal-subtraction technique. In this method, the template spectra were first broadened by an arbitrary amount before being cross-correlated against the BV Cen spectra, allowing a first iteration on the radial velocity curve of
BV Cen. The BV Cen data were then orbitally corrected using the results of this radial velocity analysis and averaged. The template spectra were once more broadened by different amounts in steps of 0.1 km s\(^{-1}\), multiplied by a constant, \(f\), and then subtracted from the orbitally corrected mean BV Cen spectrum. The broadening that gave the minimum scatter in the residual optimally subtracted spectrum was then applied to the template spectrum and the whole procedure repeated until the rotational broadening value no longer changed. This typically took two or three iterations.

Through the above process, a cross-correlation function (CCF) was calculated for each BV Cen spectrum. A radial velocity curve can then be derived by fitting a sinusoid through the CCF peaks. Unfortunately, none of our spectral-type templates provided a good match to the BV Cen spectra, all requiring a multiplication factor \(f > 1\), which would imply that the secondary star contributes more than 100 per cent of the system light. We also discovered that our G5IV template star HD 220492 is actually a close binary (see Section 5.2).

Fortunately, as discussed in Watson et al. (2006), the CCFs calculated are insensitive to the use of an ill-matching spectral template and, despite requiring multiplication factors \(f > 1\), the broadened template spectra still provided visually acceptable matches to the orbitally corrected BV Cen spectrum. The radial velocity curve in Fig. 4 was obtained after cross-correlation of the BV Cen spectrum with the G8IV star HD 217880 (our best-guess spectral type for BV Cen). This allowed us to obtain a new zero-point for the ephemeris of

\[
T_0 = \text{HJD 245 } 3195.2859 \pm 0.0003
\]

with the orbital period fixed at \(P = 0.611179\) d (from Gilliland 1982). This ephemeris was applied to the rest of the data presented in this paper.

Cross-correlation with the G8IV template yielded a secondary star radial velocity amplitude of \(K_2 = 137.3 \pm 0.3\) km s\(^{-1}\), a systemic velocity of \(\gamma = -20.3 \pm 0.2\) km s\(^{-1}\) and a rotational broadening \(v \sin i = 95.3\) km s\(^{-1}\) (see Section 6 for a discussion of the binary parameters). These values were consistent within 2 km s\(^{-1}\) for all the spectral-type templates used. Since some of our spectral-type templates (including the G8IV template star HD 217880) did not have measured systemic velocities, we carried out LSD (see Section 3) on each template star. The systemic velocity was then measured using a Gaussian fit to the sharp LSD profile; the results are listed in the final column of Table 1. We note that Gl 863.3 has a published systemic velocity (\(+66.9 \pm 0.1\) km s\(^{-1}\); Nordström et al. 2004) which is close to our measured value of \(+67.28 \pm 0.10\) km s\(^{-1}\) using this technique.

5.1 The binarity of HD 220492

While measuring the systemic velocities of the spectral-type templates, we discovered that the G5IV spectral-type template HD 220492 is a close binary system. The LSD profile of this system is shown in Fig. 5 and clearly shows two heavily broadened stellar line profiles. It is most likely that this is a close binary system containing an early to mid G-type star and later-type companion. We note that the binary nature of HD 220492 was missed by the Geneva–Copenhagen survey of the solar neighbourhood, since no radial velocity measurements of this star appear to have been taken (Nordström et al. 2004). HD 220492 is also listed as the optical counterpart to the X-ray source 1RXS 232426.0–450906 (Schwote et al. 2000), and was identified as a suspected variable star by Samus et al. (2004). Given the large \(v \sin i\) and hence rapid rotation of these stars, both components are likely to be magnetically active. Unfortunately, since only four spectra over 7 min were taken, nothing can be said about the orbital period of this system.

6 SYSTEM PARAMETERS

The system parameters (systemic velocity \(\gamma\), orbital inclination \(i\), secondary star mass \(M_2\) and primary star mass \(M_1\)) of BV Cen have been determined using the same method as described in Watson et al. (2006). In short, adopting the incorrect parameters causes artefacts to appear in the Roche tomograms leading to an increase in the structure (and hence a decrease in the entropy) of the final image. This can be visualized as an entropy landscape (see Fig. 6), in which reconstructions to the same \(\chi^2\) are carried out for different combinations of component masses and the entropy obtained for each set plotted on a grid of \(M_1\) versus \(M_2\).

In order to search for the correct set of parameters, we have constructed a series of entropy landscapes for different inclinations and systemic velocities. This is done in an iterative manner by first constructing entropy landscapes for a sequence of systemic velocities for a fixed inclination. The optimal systemic velocity found in this first iteration was then fixed and a series of entropy landscapes were then calculated out over a range of orbital inclinations. Once an optimal orbital inclination was determined, another sequence of entropy landscapes were carried out over a range of systemic velocities to ensure that the optimal systemic velocity had not changed. As we have
found previously (Watson et al. 2003, 2006), the systemic velocity obtained in this way is largely independent of the orbital inclination assumed in the reconstructions.

For the reconstructions of BV Cen, we have adopted a root-square limb-darkening law of the form

\[ I(\mu) = I_0(1 - a_1(1 - \mu) - b_1(1 - \sqrt{\mu})), \]

where \( \mu = \cos \gamma \) (\( \gamma \) is the angle between the line of sight and the emergent flux), \( I_0 \) is the monochromatic specific intensity at the centre of the stellar disc, and \( a_1 \) and \( b_1 \) are the limb-darkening coefficients at a wavelength \( \lambda \). We calculated an effective central wavelength of 5067 Å for our spectroscopic observations using

\[ \lambda_{cen} = \sum \left( \frac{1}{\sigma_i^2} \right) d_i \lambda_i \sum \frac{1}{\sigma_i^2} d_i, \]

where \( d_i \) and \( \sigma_i \) are the line-depths and error on the observed data at a wavelength position \( \lambda_i \), respectively. This therefore takes into account the line-depths and noise in the spectrum. Limb-darkening coefficients for a star of \( T_{eff} = 5250 \) K and \( g = 3.5 \) (corresponding to a G8IV star – Dall, Bruntt & Strassmeier 2005) were obtained from Claret (1998) for the \( B \) and \( V \) bands. The values of the coefficients at these wavelengths were then linearly interpolated over to find \( a = 0.5388 \) and \( b = 0.3088 \) for the effective central wavelength of our observations. These coefficients were used for all the reconstructions carried out for this paper.

Fig. 7 shows the peak entropy value obtained in entropy landscapes constructed assuming an orbital inclination of \( i = 53^\circ \) (this value was obtained after carrying out the iterative procedure described above) but varying the systemic velocity. This yielded an optimal value of \( \gamma = -22.3 \) km s\(^{-1}\). We cannot assign a rigorous error estimate to the systemic velocity but we found that the image quality depended heavily on the assumed systemic velocity, and reconstructions were almost impossible for assumed systemic velocities that differed by more than \( \pm 2 \) km s\(^{-1}\) from the optimal value. Indeed, for this reason we sampled the systemic velocity more finely than for AE Aqr (Watson et al. 2006), incrementing in steps of 0.1 km s\(^{-1}\). It is unlikely therefore that the error on the systemic velocity exceeds \( \pm 1 \) km s\(^{-1}\) and is probably less than this.

Our value of \( \gamma = -22.3 \) km s\(^{-1}\), while close to the value of \( \gamma = -20.3 \pm 0.2 \) km s\(^{-1}\) derived from the radial velocity analysis performed in Section 5, is in stark contrast to the two previous published values known to us. These are \(-47 \pm 10 \) km s\(^{-1}\) (Vogt & Breysacher 1980) and \(-47 \pm 2 \) km s\(^{-1}\) (Gilliland 1982). We are uncertain as to the cause of this discrepancy. It is unlikely that surface inhomogeneities, such as those caused by irradiation from the accretion regions (and which is known to cause systematic errors in radial velocity measurements – e.g. Davey & Smith 1992; Watson et al. 2003), could cause this discrepancy. First, our systemic velocity derived from a radial velocity analysis differs from that derived from the entropy landscape method by only 2 km s\(^{-1}\), which implies that inhomogeneities on the surface of BV Cen have little impact. Secondly, one could argue that during the observations of Vogt & Breysacher (1980) and Gilliland (1982) the impact of irradiation may have been much greater. In the case of HU Aqr, which is heavily irradiated, we found that the systemic velocity measured by standard radial velocity analyses could be shifted by as much as \( -14 \) km s\(^{-1}\) from the true value (Watson et al. 2003). Such a shift, if applicable to BV Cen, would bring the results of Gilliland (1982) and Vogt & Breysacher (1980) into closer agreement with ours but only if a large portion of the leading hemisphere (the side of the star as seen from \( \phi = 0.75 \)) was irradiated during their observations. The light curve of Vogt & Breysacher (1980) does indicate that the system was slightly brighter during their observations, but the system was certainly not in outburst and we would not expect a large amount of irradiation of the donor star. Furthermore, looking at our Roche tomograms in Section 7, irradiation of BV Cen appears to be fairly low, and certainly not large enough to impact a radial velocity curve analysis to the extent needed to bring our values of the systemic velocity into agreement, nor do we believe that our wavelength calibration is incorrect, as we have measured the systemic velocity of GI 863.3 using LSD and found it to be in agreement with Nordström et al. (2004) to within 0.4 km s\(^{-1}\) (see Section 5). Therefore, we have no satisfactory explanation of the discrepancy between our measured systemic velocity and those of Vogt & Breysacher (1980) and Gilliland (1982).

Fig. 8 shows the maximum entropy values as a function of the orbital inclination assuming the systemic velocity of \( \gamma = -22.3 \) km s\(^{-1}\) derived earlier. This shows a clear trend with the best-fitting inclination at \( i = 53^\circ \) which we have adopted as the optimal value for BV Cen. This value is lower than (but agrees to

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**Figure 6.** The entropy landscape for BV Cen, assuming an orbital inclination of \( i = 53^\circ \) and a systemic velocity of \( \gamma = -22.3 \) km s\(^{-1}\). The dark regions indicate component masses for which no fit to the target \( \chi^2 \) could be found. The cross marks the position of maximum entropy, corresponding to component masses of \( M_1 = 1.18 \) M\(_{\odot}\) and \( M_2 = 1.05 \) M\(_{\odot}\).

**Figure 7.** Points show the maximum entropy value obtained in each entropy landscape as a function of systemic velocity, assuming an orbital inclination of 53\(^\circ\). The solid curve is a fifth-order polynomial which is only shown to emphasize the trend between entropy and systemic velocity. The highest data point corresponds to a systemic velocity of \( \gamma = -22.3 \) km s\(^{-1}\).
within $2\sigma$ with) the orbital inclinations of $62^\circ \pm 5^\circ$ and $61^\circ \pm 5^\circ$ of Gilliland (1982) and Vogt & Breysacher (1980), respectively.

The entropy landscape for BV Cen carried out with $i = 53^\circ$ and $\gamma = -22.3\,\text{km\,s}^{-1}$ is shown in Fig. 6. From this we derive optimal masses for the white dwarf and secondary star of $M_1 = 1.18$ and $M_2 = 1.05\,\text{M}_\odot$, respectively. These values for the binary parameters seem to fall in between the previously published ones. Vogt & Breysacher (1980) also find relatively high masses for the binary components of $M_1 = 1.4 \pm 0.2$ and $M_2 = 1.4 \pm 0.2$. Indeed, their derived white dwarf mass places it uncomfortably close to the Chandrasekhar limit while our new estimate lies more comfortably within the allowed mass limit for white dwarfs. On the other hand, Gilliland (1982) find lower masses of $M_1 = 0.83 \pm 0.1$ and $M_2 = 0.9 \pm 0.1$. These masses, however, lead to a high mass ratio ($q = M_2/M_1$) of $q = 1.08 \pm 0.18$, which places BV Cen near the critical mass ratio for mass-transfer instability (Politano 1996; Thoroughgood et al. 2004). Our higher secondary star mass, and lower mass ratio ($q = 0.89$) move BV Cen comfortably within the region where mass transfer is stable. We should note that, since the optimal inclination we find is quite low, a small error in the derived inclination leads to quite a large error in the masses. As expected, we find that the optimal masses in our entropy landscapes vary as $\sin^2 i$.

Selection of the correct $\chi^2$ to aim for during the reconstructions is somewhat subjective. We select the $\chi^2$ which results in a close fit to the data (all reconstructions were carried out to $\chi^2 = 2.5$, which indicates that our propagated errors are underestimated but this does not impact the final reconstructions), but not so close as to cause the Roche tomograms to break up into noise. In order to determine how robust the derived parameters are, we have explored the effects that changing the target $\chi^2$ has on the entropy landscapes. We find that fitting more closely to the data causes the maps to start to break up into noise, but we find that the derived inclination is the same ($i = 53^\circ$), and the masses for each entropy landscape are typically within $\pm 0.02\,\text{M}_\odot$, and we never see a difference greater than $\pm 0.04\,\text{M}_\odot$ for any assumed inclination. The same is true if we raise the target $\chi^2$ (poorer fit to the data), except we lose sensitivity to the inclination. Despite this, even fitting to substantially higher values of $\chi^2$ where the maps become featureless we still find a preference for inclinations between $\sim 52^\circ$ and $\sim 60^\circ$. We are therefore confident in the robustness of our derived binary parameters.

Calculating the errors on our derived parameters is difficult. One could perform a series of Monte Carlo simulations of the data and carry out entropy landscape reconstructions for each synthetic data set. Unfortunately, this would require a large amount of time to complete. Instead, we can determine a rough guide to the errors from the scatter in the $v\sin \,i$ and $K_s$ values obtained from conventional analysis of the data using the spectral-type templates described in Section 5. We found that the scatter in the measured $K_s$ and $v\sin \,i$ values was, in both cases, $\pm 2\,\text{km\,s}^{-1}$. This leads to an error on the mass ratio, $q$, of $\pm 0.04$ -- which in turn translates into an error on the component masses of $\pm 0.03\,\text{M}_\odot$. Such an error agrees with the scatter we find in the optimal values returned from entropy landscapes constructed for different values of $\chi^2$. This then gives optimal parameters of $M_1 = 1.18 \pm 0.03\,\text{M}_\odot$ and $M_2 = 1.05 \pm 0.03\,\text{M}_\odot$ at an inclination of 53$^\circ$.

Clearly, the errors in the masses are dominated by any error in the derived orbital inclination. Again, we can make a conservative estimate to the likely error in our orbital inclination. A lower limit of $i = 49^\circ$ is set by the necessity that the white dwarf mass be lower than the Chandrasekhar limit. If we assume that therefore our inclination is accurate to $i = 53^\circ \pm 4^\circ$, we find $M_1 = 1.18 \pm 0.28\,\text{M}_\odot$ and $M_2 = 1.05 \pm 0.21\,\text{M}_\odot$.

7 SURFACE MAPS

Using the parameters derived in Section 6, we have constructed a Roche tomogram of the secondary star in BV Cen (see Fig. 9). The corresponding fit to the data is displayed in Fig. 2. A number of dark star-spots are visible in the Roche tomogram. The most conspicuous of these is the high-latitude spot (common in Doppler images of rapidly rotating stars) at a latitude of $\sim 65^\circ$. Such high-latitude spots seen on rapidly rotating stars are commonly believed to be caused by strong Coriolis forces acting to drive magnetic flux tubes towards the poles (Schüssler & Solanki 1992). This spot is also similar to the large high-latitude spot seen on AE Aqr by Watson et al. (2006), not just in its latitude but also in the way that it appears towards the

Figure 8. Points show the maximum entropy value obtained in each entropy landscape for different inclinations, assuming a systemic velocity of $\gamma = -22.3\,\text{km\,s}^{-1}$. The solid curve is a fifth-order polynomial fit showing the general trend. The entropy value peaks at an orbital inclination of $i = 53^\circ$. Inclinations lower than $49^\circ$ result in an optimal white dwarf mass greater than the Chandrasekhar limit and so we have not extended the analysis to significantly lower inclinations.

Figure 9. The Roche tomogram of BV Cen. The dark grey-scales indicate the presence of either star-spots or irradiated zones. The system has been plotted as the observer would see it at an orbital inclination of $53^\circ$, except for the central panel which shows the system as viewed from above the North Pole. The orbital phase (with respect to the ephemeris of Section 5) is indicated above each panel. For clarity, the Roche tomograms are shown excluding limb-darkening. Individual spots referred to in the text are arrowed.
trailing hemisphere of the star. If such a shift in high-latitude spots on CV donor stars is common, then this hints that a mechanism is in operation that drives flux-tube emergence to this side of the star. We discuss this in more detail later.

Also prominent is a dark feature near the \( L_1 \) point. Although it is possible that this may be due to a large spot (with obvious consequences for theories that invoke star-spots to quench mass transfer), we have to consider that the secondary stars in CVs are located close to an irradiating source (the bright spot and/or white dwarf, for example). It is well known that the inner face of the secondary, and the \( L_1 \) point in particular, is often irradiated. Indeed, early single-line Roche tomography studies of CVs concentrated on mapping the so-called irradiation patterns on the inner faces of the secondaries in CVs (e.g. Watson et al. 2003). While it is largely the contrast between the immaculate photosphere and lower spotted continuum contributions that cause spots to appear dark on our tomograms, irradiation causes the absorption lines to weaken due to ionization and hence also appears dark.

We believe that the feature near the \( L_1 \) point in BV Cen is indeed due to irradiation. This interpretation is supported by the modelling of \( B - V \) light curves by Vogt & Breysacher (1980) who found evidence for a slightly enhanced temperature around the inner Lagrangian point. Gilliland (1982) also found evidence for a slightly heated inner face. A close inspection shows that the irradiation pattern is asymmetric, with the impact of irradiation strongest towards the leading hemisphere. This is very similar to the irradiation pattern seen on the dwarf nova IP Peg (see Watson et al. 2003 and Davey & Smith 1992) which has been explained by irradiation from the bright spot which is located on the correct side of the star to create this asymmetry. Certainly, the light curves of BV Cen (e.g. Vogt & Breysacher 1980) show a prominent bright spot component. Also Vogt & Breysacher (1980) suggested that the \( B - V \) variations could be explained if a small region of the star nearest to the gas stream and bright spot had a temperature excess of \( \Delta T \sim 300 \) K. The location of this heated region described by Vogt & Breysacher (1980) matches what we observe in the Roche tomogram.

Several other features in the Roche tomogram are also worth mentioning. One of these is a mid-latitude spot best seen at phase \( \phi = 0.75 \) (marked as spot A in Fig. 9), which we have mentioned as it is one of the largest spots, other than the pole spot. Interestingly, there also seem to be two low-latitude spots near the \( L_1 \) point (spots ‘B’ and ‘C’ in Fig. 9), but located on the leading hemisphere. Although these spots are fairly heavily smeared in latitude, they may be located at a sufficiently low latitude to cross the mass-transfer nozzle. It has been suggested that star-spots are thought to be able to quench mass transfer as they pass the mass-losing nozzle on the donor, resulting in the low states observed in many CVs (see Livio & Pringle 1994; King & Cannizzo 1998). The observations of low-latitude star-spots near the \( L_1 \) point lend some credence to these models – it seems apparent that sizeable star-spots, which are often seen at high latitudes on rapidly rotating stars, can also form at low latitudes near the \( L_1 \) point in binaries.

It is unlikely that the spots we have identified near the \( L_1 \) point are, instead, due to irradiation. This would imply that the irradiation is patchy in nature (rather than smoothly varying across the stellar surface) in order to form the dark spots we observe in the tomogram. This, in turn, would require that the irradiation is either beamed towards relatively small patches on the stellar surface, or would require a complex accretion structure shielding the majority of the stellar surface and only allowing small spot-like regions to be irradiated. We can think of no reason why the irradiation should be beamed in this manner, nor why such a complex accretion structure should exist. In addition, while the limb-darkening around the \( L_1 \) region could be incorrect by a significant degree due to the low effective gravity, again this would be a smoothly varying artefact and would not lead to dark spots on the Roche tomogram.

We also note that, when viewed from above the North Pole of the star, there seem to be quite a distinct ‘chain’ of spots. This chain leads down from the polar regions towards the \( L_1 \) point, showing a possible deflection towards the leading hemisphere with decreasing latitude. In Fig. 10, we plot an enlarged polar view of both BV Cen and AE Aqr (from Watson et al. 2006) which shows more clearly these features. A comparison with the Roche tomogram of AE Aqr shows a similar distribution of spots (we make a more detailed comparison in Section 9). The fact that we see this same ‘chain’ of spots is suggestive of a mechanism that is forcing magnetic flux tubes to preferentially arise at these locations. Given that this is on the side of the star facing the white dwarf, this may be due to the impact of tidal forces which is thought to be able to force spots to arise at preferred longitudes (Holzwarth & Schüssler 2003). In a recent Doppler image of the pre-CV V471 Tau, Hussain et al. (2006) also found the presence of high-latitude spots located on the side of the star facing the white dwarf.

In addition to the features outlined above, a number of other small spots are visible. We have examined the intensity distribution of the pixels on our Roche tomogram in order to make a more quantitative analysis of the spot distribution. In our Roche tomography study of AE Aqr (Watson et al. 2006), we looked for a bimodal distribution in pixel intensities and labelled the population of lower intensity pixels as spots, and higher intensity pixels as immaculate photosphere. Unfortunately, unlike AE Aqr, BV Cen does not show a clear bimodal distribution in pixel intensities from which we can confidently distinguish between immaculate and spotted photosphere (note that we neglected regions that are not visible and therefore have pixel intensities set to the default value). Instead, the histogram of pixel intensities shows a broad peak, with long tails towards high and low pixel intensities. We have therefore defined a spot intensity by examining the polar spot feature. At the centre of the polar spot, the pixel intensities are very stable, and we have taken the intensity of the central regions of the polar spot to represent the intensity of a 100 per cent spotted region. Although there are lower intensity pixels present in the Roche tomogram (which contribute to the tail of low-intensity pixels in the maps), all of these were found to be confined to the irradiated zone near the \( L_1 \) point. (We should note that the fact that the region around the \( L_1 \) point has pixel intensities

![Figure 10. Roche tomograms of the donor stars in AE Aqr (left-hand panel – from Watson et al. 2006) and BV Cen (right-hand panel) as viewed from above the pole (indicated with a cross). Both show a high-latitude spot displaced towards the leftmost (trailing) hemisphere (the orbital motion is towards the right-hand panel). Furthermore, both appear to show a chain of spots descending from the polar spot towards the \( L_1 \) point.](image-url)
quite different from those of the spotted regions supports our interpretation that this feature is not a spot. We are therefore reasonably confident in our identification of the spotted regions on BV Cen.

Determining the immaculate photosphere was somewhat more difficult. There appear to be some bright regions in the map, especially near the polar spot. It is unlikely that these represent the immaculate photosphere; the growth of bright pixels in maps that are not ‘thresholded’ is a known artefact of Doppler imaging methods (e.g. Hatzes & Vogt (1992) – also see Section 4), and it is likely that these features are due to this, contributing to the long tail of bright pixel intensities that we see. Instead, we have selected the intensity at the upper end of the broad peak of pixel intensities in the histogram to represent the immaculate photosphere. If we assume that the appearance and disappearance of spots simply alters the continuum level (and not the line-depths, which have a secondary influence on the LSD profiles) and a blackbody scaling, this gives a temperature contrast between the photosphere and spot of $\Delta T = 780$ K. Such a temperature difference seems reasonable. From simultaneous modelling of light curves and line-depth ratios of three active RS CVn systems, Frasca et al. (2005) found a temperature difference between spotted and immaculate photosphere of $\Delta T = 450$–850 K. Similarly, Biazzo et al. (2006) find temperature differences of $\Delta T = 453$–1012 K for stars at different locations along the Hertzsprung–Russell diagram, with stars of lower surface gravity having spots with a lower $\Delta T$.

Each pixel in our Roche tomogram was given a spot filling factor between 0 (immaculate) to 1 (totally spotted) depending on its intensity at our predefined immaculate and spotted photosphere intensities. After removal of the region near the $L_1$ point (which is caused by irradiation and would cause us to overestimate the total spot coverage), we find that some 25 per cent of the visible hemisphere of BV Cen is spotted. This figure is relatively high compared to the spot coverages returned from Doppler images of isolated stars (typically 10 per cent) and is probably due to our less-than-ideal characterization of spot filling factors compared to imaging codes that invoke two-temperature models. However, a visual comparison of BV Cen with the map of AE Aqr (Watson et al. 2006 – for which we had estimated an 18 per cent spot coverage) clearly shows that the appearance and disappearance of spots simply alters the continuum level (and not the line-depths, which have a secondary influence on the LSD profiles) and a blackbody scaling, this gives a temperature contrast between the photosphere and spot of $\Delta T = 780$ K. Such a temperature difference seems reasonable. From simultaneous modelling of light curves and line-depth ratios of three active RS CVn systems, Frasca et al. (2005) found a temperature difference between spotted and immaculate photosphere of $\Delta T = 450$–850 K. Similarly, Biazzo et al. (2006) find temperature differences of $\Delta T = 453$–1012 K for stars at different locations along the Hertzsprung–Russell diagram, with stars of lower surface gravity having spots with a lower $\Delta T$.

Differences of $\Delta T$ /$\Delta\,\!$ T between our predefined immaculate and spotted photosphere range from 0 (immaculate) to 1 (totally spotted) depending on its intensity at the upper end of the broad peak of pixel intensities in the histogram to represent the immaculate photosphere. If we assume that the appearance and disappearance of spots simply alters the continuum level (and not the line-depths, which have a secondary influence on the LSD profiles) and a blackbody scaling, this gives a temperature contrast between the photosphere and spot of $\Delta T = 780$ K. Such a temperature difference seems reasonable. From simultaneous modelling of light curves and line-depth ratios of three active RS CVn systems, Frasca et al. (2005) found a temperature difference between spotted and immaculate photosphere of $\Delta T = 450$–850 K. Similarly, Biazzo et al. (2006) find temperature differences of $\Delta T = 453$–1012 K for stars at different locations along the Hertzsprung–Russell diagram, with stars of lower surface gravity having spots with a lower $\Delta T$.

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Based on our spot characterization scheme outlined above, we have determined the distribution of star-spots as a function of latitude scaled either by the total surface area of the star, or by the surface area of the latitude strip over which the spot coverage was calculated (see Fig. 11). This shows that the highest spot filling factor is achieved at polar latitudes, primarily due to the large high-latitude spot centred at $+65^\circ$. We also find that the spot coverage reaches a minimum at intermediate latitudes around $\sim 45^\circ$. This is also very similar to what was found for AE Aqr (Watson et al. 2006), though the drop in spot coverage at this latitude is far more evident in BV Cen than in AE Aqr.

Fig. 11 also shows clear evidence for a bimodal distribution of star-spots with latitude. Our analysis indicates a lower latitude site of spot emergence around $25^\circ$: indeed the majority of spots seem to form at lower latitudes in BV Cen. In our Roche tomography study of AE Aqr (Watson et al. 2006), we found some evidence for spots at lower latitudes, although this was somewhat uncertain given the low S/N of those observations. While the BV Cen data have large phase gaps, this time we can be confident that we are seeing spots at lower latitudes. Many of the features described here, such as the off-pole high-latitude spot, the bimodal spot distribution and the relative paucity of spots at intermediate latitudes are also seen in Doppler images of a number of other stars (see the discussion in Watson et al. 2006 and references therein). What is most startling, however, is the great similarity between the maps of AE Aqr presented in Watson et al. (2006), and those of BV Cen presented in this work.

Finally, we have checked whether the features seen in the Roche tomogram are real, or artefacts due to noise. We carried out two further Roche tomography reconstructions, the first only using the odd-numbered spectra, and the other using the even-numbered spectra. These are both shown in Fig. 12 and, despite the reduction in phase coverage, both maps show the same features. We are therefore confident that the features in the Roche tomogram are not due to noise.

8 A SLINGSHOT PROMINENCE?

In addition to the many star-spot signatures that are visible in BV Cen’s trailed spectra (see Fig. 3), a curious narrow feature is also
evident between phases 0.328 and 0.366 on the blue edge of the profile. This feature appears as a narrow continuation of the main track through the profiles during this block of observations, but lies outside the stellar absorption profile and therefore cannot lie on the stellar surface. A closer inspection of the individual profiles (see Fig. 13) reveals a narrow, weak emission feature in the continuum of five LSD profiles. In order to confirm the reality of this feature, we have visually inspected the profiles that were deconvolved from the blue and red spectra separately to see whether they are present in both sets of profiles. Indeed this feature is present (albeit very weakly) in both sets of profiles which makes it unlikely to be due to noise or a systematic effect arising during the LSD process. This feature is also not due to contamination from lunar or solar light during the observations as this would appear as an absorption feature (e.g. Marsden et al. 2005). Furthermore, moon rise did not occur until at least 2 h (extending to 4 h on the final night) after observations of BV Cen were concluded. The fact that the feature is at zero velocity with respect to BV Cen’s systemic velocity of $-22 \text{ km s}^{-1}$ rules out a ‘terrestrial’ origin, which would be centred at 0 km s$^{-1}$. We are therefore confident that this feature is real.

Since the emission feature lies outside the stellar line profile, and hence lies off the stellar limb, it can only be attributed to circumstellar material. Solar prominences appear as bright emission loops when they are viewed off the solar limb, and it is probable that we are also seeing a prominence structure on BV Cen. Indeed, large prominences have been reported on other rapidly rotating stars such as AB Dor (e.g. Cameron & Robinson 1989) and Speedy Mic (Dunstone et al. 2006a) and are often observed as transient absorption features passing through the Doppler-broadened Hα stellar line. Recently, however, an analysis of Very large Telescope data of Speedy Mic by Dunstone et al. (2006b) has revealed rotationally modulated emission outside the stellar Hα line due to loops of emission seen off of the stellar disc, but which can also be associated with prominences seen to transit the stellar disc at other times. In addition, peculiar low-velocity emission features seen in SS Cyg and IP Peg during outburst have also been interpreted as ‘slingshot prominences’ (Steeghs et al. 1996). Gaensicke et al. (1998) discovered the presence of highly-ionized low velocity dispersion material located between the $L_1$ point and the centre-of-mass in AM Her which they attributed to a slingshot prominence. Similarly, triple-peaked Hα lines following the motion of the donor star in AM Her has been reported by Kafka et al. (2005) and Kafka, Honeycutt & Howell (2006). The authors interpreted these as long-lived prominences on the donor star and noted that one component was consistent with stellar activity lying vertically above the $L_1$ point.

The emission feature we see in BV Cen appears stationary at $\sim 0 \text{ km s}^{-1}$ within the binary frame. This is in keeping with the stationary slingshot prominences seen in SS Cyg and IP Peg by Steeghs et al. (1996), and the low-velocity emission observed in other CVs (Marsh & Horne 1990). Generally, we would expect the emission from prominences observed off the stellar limb to be weak and undetectable for CVs, given their faintness. However, it is possible that the prominences are illuminated by the accretion light, causing prominences forming between the donor star and the white dwarf to become visible when otherwise they would be undetectable. Certainly, the low velocity of the emission suggests a position close to the centre-of-mass of the binary at a point between the donor star and white dwarf where such illumination is most likely.

Given that prominences are normally only seen in lines that form above the photosphere (e.g. the hydrogen Balmer lines), observing them in the LSD profiles which are obtained from photospheric lines is unexpected under normal conditions. We believe that the emission seen in BV Cen’s photospheric lines is due to excitation of these species within low-density gas in the prominence due to the impact of irradiation. Thus, we suspect that irradiation not only causes the prominence to become highly visible, but also causes it to be observable in some photospheric lines in which prominences in a normal, unirradiated environment would not normally emit. We have considered that the emission could be due to a wind launched from the accretion regions. Such a wind, however, would exhibit a radial velocity modulation due to the orbital motion of the primary star which we do not observe. Furthermore, presumably the velocities of material in such a wind would produce a far broader emission line than observed in BV Cen. For these reasons, and the fact that it kinematically matches previous observations of slingshot prominences in CVs, we prefer the interpretation that this feature is the result of an irradiated prominence.

8.1 Limits on the prominence size and height

We find that the emission feature in BV Cen is very narrow, with a velocity width ($\Delta V$) of $\sim 10 \text{ km s}^{-1}$. Using this width, we can place an upper limit on the emission-source size, $L$. Following Steeghs et al. (1996), we assume that the prominence is corotating with the
increased by instrumental resolution, thermal broadening, saturation, and a vertical line centred on a radial velocity of 0 km s\(^{-1}\). Unlike Fig. 2, the orbital motion has not been removed and a vertical line centred on a radial velocity of 0 km s\(^{-1}\) has been plotted to show where the emission feature appears. The slingshot prominence feature appears outside the stellar lines on the first night’s data (top six profiles). During the second night (bottom profiles), it appears within the profiles but moves in the opposite direction relative to the star-spot features and the Roche tomography code is therefore unable to fit this feature.

### 8.2 Prominence evolution and structure

Three nights of consecutive (albeit interrupted) observations allow a limited discussion of the evolution of the slingshot prominence observed on BV Cen. The prominence is certainly seen at the start of the first night (\(\phi = 0.328–0.366\)) before it transits the stellar disc, where it then becomes invisible. We have assumed that, rather than the prominence disappearing at this point, its signature is lost in the complex structure present in the stellar line profile. We are able to pick up an emission feature with the same position in velocity space again at the start of the second night (\(\phi = 1.974–2.038\), see Fig. 13).

Curiously, this prominence feature then disappears after orbital phase 2.038. Since, unlike the first night, the prominence on the second night appears quite clearly in the middle of the stellar line profile, it is, on this occasion, difficult to explain how the feature could suddenly be lost within the stellar line. This suggests that the disappearance may be due to rapid evolution of the prominence.
of tidal forces due to the close proximity of a compact companion, and such a ‘sub-white dwarf’ concentration of spots is also seen on the pre-CV V471 Tau (Hussain et al. 2006). A concentration of star-spots on the inner face of the donor stars in CVs may also have consequences for the accretion dynamics of these objects. It has long been thought that star-spots may be able to quench mass transfer from the donor as they pass across the $L_1$ point, leading to the low states seen in many CVs (e.g. Livio & Pringle 1994; King & Cannizzaro 1998). Indeed, in their study of the mass-transfer history of AM Her, Hessman, Gänscicke & Mattei (2000) concluded that such a model would require an unusually high spot coverage near the $L_1$ point, or otherwise some mechanism that drives spots towards the $L_1$ point. Certainly, both AE Aqr and BV Cen do seem to show increased spot coverages towards the $L_1$ point in support of their conclusions.

The fact that we see more active regions near the $L_1$ point may also explain why we appear to see a preference for ‘slingshot prominences’ to form above the donors’ inner face (Steeghs et al. 1996; Gaensicke et al. 1998; Kafka et al. 2005, 2006 – and again in this work). Certainly, the fact that prominence material at these locations will be illuminated by the accretion regions also means that observations will be biased towards detecting prominences in the region between the white dwarf and donor star in CVs. Furthermore, if surface magnetic fields are strong enough in the neighbourhood of the $L_1$ point this may also cause fragmentation of the mass flow, resulting in the inhomogeneous or ‘blobby’ accretion seen in some CVs (e.g. Meintjes 2004; Meintjes & Jurua 2006).

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